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dominance approach

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Measuring human development: a stochastic dominance approach

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Abstract

We consider a weighting scheme that yields the best-case scenario measurement of the Human Development Index (HDI) using an approach that relies on consistent tests for stochastic dominance efficiency (SDE). We compare a given hybrid composite index such as the official equally-weighted HDI to all possible indices constructed from a set of individual components to obtain the most optimistic scenario for development. In the best-case scenario index education is weighted considerably more than the other two components, per capita income and life expectancy, relative to the weight that it gets in the official equally-weighted index. We find that the best-case scenario hybrid index leads to a marked improvement of measured development over time when compared with the official equally-weighted HDI.

EL Classifications: C12; C13, C15; O15; O57

Key Words: Nonparametric Stochastic Dominance; Human Development Index; Mixed Integer Programming

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1 Introduction

It has been recognized that welfare analysis based on a single attribute is inadequate and as a result recent developments in welfare economics emphasize multivariate methods (see, e.g., Maasoumi (1999); Fleurbaey (2009) for an overview). In this context, a basic needs approach contends that individual well-being and social welfare depend on the joint distribution of various attributes, such as income, health and education. Traditionally, welfare analysis of multiple attributes is often undertaken by examining each individual attribute separately. However, this approach fails to account for the relationship between the various attributes. Alternatively, another method is to construct a single welfare index as an aggregate of multiple sub-indices, each of them capturing a single attribute. In this category we have the United Nations Development Program's Human Development Index (HDI), which is the arithmetic average of an income index, an education index and a health index. This is a summary composite index that measures a country's average achievements in three basic aspects of human development: longevity, knowledge and a decent standard of living *using fixed equal weights* to reflect the desire to attach equal importance to each of the above dimensions.¹

A serious shortcoming is that the construction of the above composite measure, as in the case of the separate analysis of single attributes, ignores the dependence among the various attributes. Furthermore, each sub-index is obtained as a transformation of raw components, which in turn will have an effect on the implicit weights used to arrive at the overall index.² For example, Noorbakhsh (1998, p. 522) highlights the importance of the normalization procedure of raw data into an index stating that "if the difference between a upper and lower bound is relatively high for one component and relatively low for another component then the effect of the former on the composite index becomes somewhat lower than that

¹Each component is expressed as an index taking outcomes between 0 and 1. We are using the term "fixed equal weight HDI" in the paper to denote that each component (index) is weighted equally to construct the standard HDI.

²The transformation of raw components into an index until 2010 is defined as follows. The value of a country's life expectancy index is obtained by the country's life expectancy in years minus 25 divided by 60, for a number that would lie between 0 and 1. The education index (E) is defined as $E = \frac{2}{3}(\text{adult literacy index}) + \frac{1}{3}(\text{gross enrolment index})$. This index is constructed so that a 2/3 weight is given to literacy (percentage of the population that is considered literate) and a 1/3 weight is given to gross school enrollment as a percentage of the eligible school age population and it is bounded between 0 and 1. The GDP per capita index is defined as, $\text{GDP Index} = \frac{\log(\text{GDP per capita}) - \log(100)}{\log(40000) - \log(100)}$. Please note that for the application purposes of this paper, we consider the old formulation of the HDI which is used until 2010. After 2010, the construction of the official HDI has changed and the new formulation of the HDI is discussed in section 6.1, see footnote 11.

of the latter”. Ravallion (1997) also suggests that two countries can reach the same HDI, yet one may rely more on economic growth while the other on attainments in health care and schooling. He calculates trade-offs between longevity and income and found that HDI’s implicit valuation of one year of life expectancy is much lower in poor countries and a lot higher in rich countries. Therefore, even though each sub-index is weighted equally after converting the raw components into an index, each index has different implicit weights for different dimensions of human development. In this paper, we will adopt a data driven alternative weighting scheme to arrive at a composite index that will shed a different light on this issue. We will follow an approach to the construction of aggregate indices based on stochastic dominance (SD hereafter) analysis that avoids the problems mentioned above.

SD offers an approach for data analysis that is used in a wide variety of applications in economics. It provides an effective and viable tool for comparing welfare distributions, the main focus in this article. It aims at comparing random variables in the sense of stochastic orderings expressing the common preferences of rational decision-makers. Stochastic orderings are binary relations defined on classes of probability distributions. They translate mathematically intuitive ideas like “being larger” or “being more variable” for random quantities. The main attractiveness of the SD approach is that it is nonparametric, in the sense that its criteria do not impose explicit functional form requirements on individual preferences or restrictions on the functional forms of probability distributions.³ An important reason why SD has not been applied before in the construction of an index is the restriction that until recently, SD efficiency (SDE hereafter) could only be tested pair-wise. In the next section we discuss some of the issues that arise in that context and the relevant literature.

The weights derived from SD analysis can be thought of as explicit weights that lead to the most optimistic development scenario. In this context, the dimension that gets relatively more weight is the one in which most countries realize higher relative levels of measured welfare. There are two possible reasons for this to happen. Firstly, welfare improvements in that dimension may be reached faster over-time relative to the other dimensions. Hence, if improvements in a given dimension can be achieved faster by all or most countries, more emphasis would be given to the other dimensions that are slow to respond in reaching their targeted levels for further welfare improvements to occur. Secondly, it may be the case that the normalization procedure of the raw components in that dimension allows countries to achieve targeted goals relatively faster than in the other dimensions (e.g., the upper and

³In a related work, Shorrocks (1983) analyzes a partial welfare ordering of income distributions which is consistent with a dominance relation of the generalized Lorenz curves. It is shown that in an one dimensional setting, the dominance for concave and increasing utility functions, i.e., second-order SD, is equivalent to generalized Lorenz dominance, see also Kakwani (1984).

lower bounds of the raw components in that dimension are set in such a way as to reach a higher implicit weight in that dimension). We employ two complementary SD approaches to examine the reasons mentioned above. To assess the former explanation, we employ SD analysis to examine whether there has been a general improvement in the official HDI and its components over-time. In that regard we will be able to obtain information on the dimensions in HDI that are fast-responding (slow-responding) in reaching their targets for all countries involved. For the latter explanation, SD analysis also sheds light on the weights given to the constituent sub-indices of these dimensions through their construction from raw components. In this sense, SD analysis can also be considered as an assessment tool of the different dimensions that are being used for relative welfare comparisons.

A natural application of the SD approach arises when there exists already an index with a particular set of weights for its sub-indices, as in the case of the official HDI. A given set of weights for each sub-index (e.g., equal weights to each sub-index for the official HDI) offers a certain level of development to each country. However, any valid choice of different weights assigned to each sub-index may not only correspond to different levels of development for some countries, but also may increase (decrease) the overall level of measured development. In that case, there are infinitely many choices of alternative weighting schemes, each of them resulting in a different ranking. Choosing among all possible weighting schemes is the focus of our paper. We take the official HDI as the benchmark and we apply the SD approach to derive weights assigned to each sub-index that result in the highest possible measured level of development among all possible alternatives when compared with this benchmark. To do so, the SD approach maximizes the distributional distance between the given (equally-weighted) index, namely the official HDI, and any possible alternative. SD analysis allows us to derive the best-case scenario weighting scheme, where more countries achieve higher measured development levels and lower variability both cross-sectionally and over-time than any possible alternative.⁴ As a result our approach sheds light on the indicators that are driving or holding back an overall improvement in measured welfare when the chosen measure is the official HDI. In other words, the indicators that are assigned high (low) weights with the SD approach are the ones which are found to be driving (holding back) a general improvement in measured human development.⁵

⁴One can also find the most pessimistic development scenario by reversing the order of the two cumulative distribution functions in the maximization problem, which amounts to changing the sign of the argument in the problem, see the third section of the paper. In that case, applying SD analysis in reverse would result in the most pessimistic worst-case development scenario. This weighting scheme on the other hand would be informative about which indicators are holding back overall improvement in the conventional HDI.

⁵Space restrictions and construction of the SD tests for the most optimistic case preclude us to

It is worth mentioning that the best-case scenario weighting scheme that we obtain in this paper is derived from the nature of the SD optimization problem (i.e., a data analytic statistical criterion) and refers to the “measured” level of development and not the true “optimal” one. The true “optimal” human development is a very dynamic and complex concept which requires a philosophical, social and political discussion as well as the use of a specific social welfare function or criterion. For example, the latter could be based on an explicit welfare optimality criterion such as the golden rule implied by an extended Solow model (see Engineer and King (2010)), whereas in our case maximization of the measured level of development leads to the best-case scenario for development. In our analysis, we take the choice of components or dimensions as given and we look at what constitutes the most optimistic scenario given the choice of these welfare components, whereas in the former case the welfare criterion may lead to alternative dimensions of development (such as replacing per capita income by per capita consumption for example). Streeten (1994) discusses the conceptual aspects of human development and suggests that “the concept of human development is much deeper and richer than what can be caught in any index or set of indicators”. Lai (2000) acknowledges that human development is “intrinsically political”. Streeten (1994), on the other hand, remarks on the importance of the measurement of human development in a multidimensional manner, such as HDI, suggesting that those indices catch the public attention and expose the narrow and incomplete nature of unidimensional indices, such as GDP. In this paper, we examine the dynamics of the HDI (e.g., improvements of the official HDI and its components over time) and the implications of the most optimistic weighting scheme (e.g., assessment of the importance and adequacy of the different dimensions in the official HDI) for relative welfare comparisons.

This paper’s findings have important implications. First of all, the results suggest that there is no general improvement for any index using a five-year testing horizon (subperiods within 1975 to 2000). However, apart from the GDP index, all other indices display significant improvements using a ten-year horizon. In almost all 10 year or greater periods, there is dominance at first-order at the 1% significant level, for education and life expectancy, although not as strong for the latter as for the former. Moreover, there is no general improvement in the life expectancy index between the period 1990 and 2000. However, for the GDP index, there are no discernible significant general improvements over the whole period. In other words, the improvement in the official HDI over-time is mainly driven by the improvement in the education index, the fast-moving or fast-responding indicator to its

represent detailed analysis of the most pessimistic results in the current paper; however, the results of such investigation can be obtained as suggested in footnote 4. Furthermore, dimensions having lower weights with the most optimistic case scenario already shed a light on the pessimistic case.

targets for all countries over the ten-year horizon periods. Life expectancy and the GDP index are the slow-moving indicators responsible for holding back the overall improvement in the official HDI, GDP being the slower of the two.

The over-time improvement in the education index complements the other finding of the paper that the most optimistic view of the relative levels of human development, across countries and over time is obtained by weighting the education index dimension considerably more than life expectancy and the GDP per capita index. The results of the paper suggest that anyone inclined, on prior grounds, to weight education more strongly than does the HDI, would tend to take a more optimistic view of the extent of a general improvement in welfare. With the best-case optimistic weighting scheme we arrive at new country rankings that are quite different from the ones obtained using the standard equally-weighted HDI. The rankings based on SDE are more stable as they are based on a choice of weights that minimizes the variability across countries and over time. Countries that achieve consistently higher levels in each component do not experience dramatic changes. On the one hand, we find that countries with a good education system but with a low standard of living (e.g., countries that were part of the old Soviet Union) move up in the rankings. On the other hand, countries with a higher living standard, but with a weak education system (e.g., resource-dependent economies) move down in the rankings. High gender inequality (i.e., low female participation in the educational system) could be one of the main factors behind the weakness of the educational system in these countries.

The remainder of the paper is as follows. In section 2, we present the debate regarding the construction of HDI and the purposes that it serves. In section 3, we examine the main framework of analysis. We define the notions of SD and we discuss the general hypothesis for SD of any order. We follow Barrett and Donald (2003), hereafter BD, to describe the test statistics and their asymptotic properties. In section 4, we present the mathematical formulations of the tests. In section 5, we present some simulations to show the importance of least variability over time for the efficiency of the index and the robustness of the results. In section 6, we present the empirical application, where we use consistent SD tests from both BD and Linton et al. (2005) to examine the welfare improvements in the separate components and in the official HDI and we employ the Scaillet and Topaloglou (2010), hereafter ST, methodology to obtain the most optimistic weights for the different constituent components. Finally, we conclude in section 7. Proofs and detailed mathematical programming formulations are gathered in an appendix, where we also discuss practical ways to compute p-values for testing stochastic dominance at any order by looking at bootstrap and block bootstrap methods.

2 Literature

GDP (or GNP) per capita has traditionally been used as an indicator of the level of development for comparisons among countries and within a country. There has been a long debate on the appropriateness of GNP per capita as a development indicator.⁶ Sen (1985, 1987) maintains that income itself, things which can be exchanged for income, and things which can be thought of as income must be distinguished from what he calls “functionings”. Functionings are “features of the state of existence of a person”, not things which the person or the household can own or produce. He indicates that “capabilities” are the alternative types of functionings from which a person can choose what he calls “refined functionings” and he argues that the main element that characterizes the concept of standard of living is that of functionings and capabilities, not that of direct opulence, commodities or utilities. In this context, a functioning is an achievement, whereas a capability is the ability to achieve. Functionings are, in a sense, more directly related to living conditions such as being in good health, being well sheltered, moving freely, or being educated. Capabilities, in contrast, are notions of freedom, in the positive sense: “what real opportunities you have regarding the life you may lead” (Sen (1987, p. 36)). Pressman and Summerfield (2000) point out that the HDI is one of the most influential scholarly attempts to measure socioeconomic development based upon key capabilities in different countries. Saito (2003) indicates that HDI is considered to be one of the ways in which Sen’s capability approach can become operational, despite the fact that there are many criticisms of this index.

One of the main criticisms of HDI has been the poor quality of data used in the construction of its constituent components that are plagued by serious measurement error problems (Hopkins 1991). Ogwang (1994) points out that many countries fail to have uninterrupted collections of census data from which information on life expectancy and literacy could be obtained. Srinivasan (1994) highlights the weaknesses of the data as for example GNP data of many developing countries suffer from problems of incomplete coverage, measurement errors and biases. Chamie (1994) points out the lack of relatively reliable and recent data for estimating life expectancy at birth for most countries in the 1980’s. Other data concerns have to do with the changes of the minimum and maximum values of each component of HDI

⁶Becker et al. (2005) argue that the use of per capita income to evaluate welfare improvements assumes that it reflects the level of economic welfare enjoyed by the average person. It is also widely acknowledged that national income constitutes an imperfect measure of social well-being (Easterlin (1995)). For example, national income includes expenditures that are needed to prevent worse outcomes (“regrettable necessities”) and ignores also the numerous components of well-being such as the enjoyment of good health, of an unpolluted natural environment, of leisure time and of political freedoms and rights (Ponthière (2004)).

over time, as in 1990, 1991, 1994 and 1995. Kelley (1991), using an alternative maximum point of life expectancy at the age of 73, demonstrates the sensitivity of HDI to the choice of minimum and maximum values of each component as he finds that 22 countries move from “low” to “medium” human development. In this paper, we also acknowledge the impact of the upper and lower bounds on the derivation of weights. Since each index is bounded between 0 and 1, higher measured development levels for more countries describe a distribution that is negatively skewed resulting in less variability cross-sectionally and over time. In that context, SDE analysis applied to scaled data would result in the most optimistic composite index in which more observations correspond to higher measured relative development levels.

However, the main criticism of the official HDI is the arbitrary equally-weighted scheme of the three components, life expectancy, education and standard of living. It has been suggested that the equally-weighted HDI and/or its components are very closely correlated with GDP or GNP per capita and as such there is a “redundancy” problem in its formation. McGillivray and White (1993) extended the analysis of McGillivray (1991) by looking for the redundancy of the HDI vis-à-vis its own components. It is indicated that HDI is least redundant when it is used to compare within similar groups of countries (i.e., grouped as high, middle and low human development). However, if HDI is used to compare all countries it adds little new information to that provided by per capita income or by any of the other components. For overall comparisons an index could well be based on any one of its three components. Along the same lines as McGillivray and White (1993), Cahill (2005) proposes alternative weighting schemes that form two sets of indices that are statistically indistinguishable and very highly correlated with the original HDI. The implication here is that a simpler HDI series based solely on one of the components would be more convenient to compute without loss of too much information. However, correlation among components does not provide any information about the development level of a country. For example, two correlated components may rank countries similarly; however, development level gaps between countries may be higher with one and lower with the other. For instance, Cahill (2005) using correlation analysis arrived at an alternative weighting scheme that is statistically indistinguishable from the official HDI, but he did not provide any information on the relative development levels this weighting scheme would entail.

An alternative approach is Principal Components Analysis (PCA) in which, from a given set of attributes, a linear combination is constructed that accounts for the largest proportion of variance in the original variable series. The first principal component is that linear combination of the original attributes which explains the highest fraction of the variance in the original variables. Ogwang and Abdou (2003) used principal components analysis to

find that the first principal component weights attached to the three HDI components are approximately equal, a result consistent with the equal weighting scheme adopted by the United Nations Development Program (UNDP) in the computation of HDI.⁷ Moreover, in the 1993 UNDP report, it is noted that the almost equally-weighted combination of components explains 88% of the variation in the original set. Srinivasan (1994), on the other hand, notes that “this finding [UNDP, 1993] says nothing about what aspects of development are being portrayed by the combination”. Moreover, variability in the original set of components may be due to problems of incomplete coverage, measurement errors, and biases and furthermore, different components suffer from different degrees of measurement error and noise (Srinivasan 1994; Biswas and Caliendo 2002) and may affect the linear combination of the attributes analyzed by PCA. The linear combination of components obtained by PCA explains the highest fraction of the variance in the original variables but does not say much about the level of measured development achieved by the principal component. Furthermore, PCA is based on the consideration of the second moment alone after standardizing for a common mean. This would be adequate if the data were characterized solely by the first two moments. That would be the case, if other features of the distribution were not important, something that is not true for the data that characterize the attributes of HDI. In contrast, the nonparametric SDE analysis that we employ relies instead on the characterization of the whole distribution and hence the results that we obtain are robust.

On the other hand, Biswas and Caliendo (2002) stress the importance of the variability of each component and state that greater variability of one component index relative to another represents information that is unused or ignored in simple averaging. In contrast to Biswas and Caliendo (2002), an index constructed using stochastic dominance efficiency tools favors the least variant index over time, since human development cannot change dramatically in relative short periods of time and improvements may only occur over longer time horizons. However, we agree with Biswas and Caliendo (2002) that simple averaging ignores the information content that is hidden in the differential improvement of each component over time.

As discussed above, there have been a number of criticisms of the construction of the official HDI. Our paper attempts to make a contribution to the empirical side of the literature rather than a conceptual discussion of what would constitute “true” human development (see Streeten (1994) for a more pertinent discussion of such an approach). In the remainder of the paper, we will try to find the weighting scheme of the different components that results in a composite HDI that offers a higher measured relative level of development and less

⁷The principal component analysis is used to compute composite indices of well-being by Ram (1982), Lai (2000), and McGillivray (2005), among others.

variability across countries and over time when compared with the equally-weighted HDI.

As mentioned in the introduction our approach will be based on SD analysis. An important reason why SD has not been applied before (based on its theoretical attractiveness) in the construction of an index is that until recently, SDE could only be tested pair-wise. This restriction was limiting the scope of SDE tests, because indices are constructed from a set of components and they effectively face infinitely many choice alternatives. We discuss how we tackle this problem below. Before testing whether the weighting scheme of the official HDI offers the most optimistic index or not, we first examine its SD behavior over a twenty-five year period and determine which factors drive its improvement over time. In examining SD over time, we rely on Kolmogorov-Smirnov type tests developed within a consistent testing environment developed by BD.⁸ Linton et al. (2005) propose a subsampling method which can deal with both dependent samples and dependent observations within samples. This is appropriate for conducting SD analysis with country panel data (as in the case of the HDI data) to examine welfare improvements over time. We use both the BD and Linton et al. (2005) frameworks to test for SD of the HDI and its individual components over a twenty-five year period.

Lately, multivariate (multidimensional) comparisons have become more popular. Duclos et al. (2006) propose nonparametric SD poverty comparisons using multidimensional attributes of well-being and derive estimators of critical poverty frontiers. For example, in the case of the sub-indices of HDI, one could derive critical levels of the education index, the life expectancy index and the GDP per capita index such that falling below these levels would result in lower overall welfare at a given year relative to another. However, Duclos et al. (2006) do not allow for differential weights of each dimension. In a similar application to optimal portfolio construction in finance, ST use SDE tests to compare a given portfolio with an optimal diversified portfolio constructed from a set of assets. We follow the same methodology, using the given set of attributes (in our case per capita income, life expectancy and a measure of human capital) to construct the most optimistic index, that does not rely on an arithmetic average of the different attributes (sub-indices).

In the next section, we will discuss consistent SD tests that allow us to determine which factors drive the improvement of human development levels over time. Moreover, we derive

⁸This offers a generalization to Anderson (1996), Beach and Davidson (1983), Davidson and Duclos (2000) who have looked at second-order stochastic dominance using tests that rely on pair-wise comparisons made at a fixed number of arbitrary chosen points. This is not a desirable feature since it introduces the possibility of test inconsistency. Davidson and Duclos (2000) have discussed the importance of first, second and third-order stochastic dominance concepts (hereafter SD1, SD2, and SD3 respectively) between income distributions for social welfare and poverty ranking of distributions.

statistics to test for SD efficiency of the official equally-weighted HDI with respect to all possible combinations of weighting schemes constructed from the set of components.

3 SD Efficiency Testing

We consider a strictly stationary process $\{Y_t; t \in Z\}$ taking values in R^3 . The observations consist of a realization of $\{Y_t; t = 1, \dots, T\}$. These data correspond to observed values of the three different constituent components of the HDI. We denote by $F(y)$, the continuous cdf of $Y = (Y_1, \dots, Y_3)'$ at point $y = (y_1, \dots, y_3)'$.

Let us consider a hybrid composite index with a weighting vector $\lambda \in L$ where $L := \{\lambda \in R_+^3 : e'\lambda = 1\}$ with e being a vector of ones. This means that all the different components have positive weights and that these weights sum up to one. Let us denote by $G(z, \lambda; F)$ the cdf of the hybrid index value $\lambda'Y$ at point z given by $G(z, \lambda; F) := \int_{R^3} \mathbb{I}\{\lambda'u \leq z\} dF(u)$.

3.1 Tests for SD of different indices

SD is a term which refers to a set of relations that may hold between distributions. SD efficiency is a direct extension of SD to the case where full diversification is allowed. In that setting we derive statistics to test for SD efficiency of the equally-weighted official HDI (with the vector of equal weights denoted by τ) with respect to all possible combinations of weighting schemes (λ) constructed from the set of components.⁹ A very common application of SD is to the analysis of welfare. In this paper we test whether the official HDI, τ , i.e., equal weights given to each sub-index, is the best-case scenario, in the sense that it gives the maximum value and lower variability of measured human development levels across countries and over time, given its constituent components (longevity, knowledge, GDP per capita), or whether we can construct another composite index λ (alternative weighting scheme) from the set of components that dominates it.¹⁰

⁹We have defined above λ and τ to be different weighting vectors that are associated with different hybrid indices. In the discussion that follows we use λ and τ interchangeably with the index that they represent.

¹⁰Assigning weights to each dimension to arrive at the most optimistic best-case scenario that describes the level of human development across countries and over time based on SD analysis has a number of advantages. Firstly, it provides an index resulting from the least variable combination of components that maximizes the measured level of development for a group of countries. Secondly, economic theory is agnostic in terms of offering us strong guidance about the functional form of preferences and distributions of the different components of human development so that it makes sense to proceed under relatively general assumptions. Thirdly, relatively large data sets are available, so that nonparametric analysis can let the data "speak for themselves".

The distribution of the hybrid index λ dominates the distribution of the index τ stochastically at first-order (SD1) if, for any argument z , $G(z, \tau; F) \geq G(z, \lambda; F)$. This definition often looks as though it is the wrong way round, but a moment's reflection shows that it is correct as stated. If z denotes a development level, then the inequality in the definition means that the proportion of countries in distribution λ with value of development smaller than z is not larger than the proportion of such countries in τ . In other words, there is at least as high a proportion of human development in λ as in τ . If the composite index λ dominates the index τ at first order, then there are always more countries having relative levels of human development below a given development level, z , in τ than in λ , so that λ achieves higher relative levels of measured development for more observations than τ . Figure 1 displays the dominance of hybrid index λ over index τ .

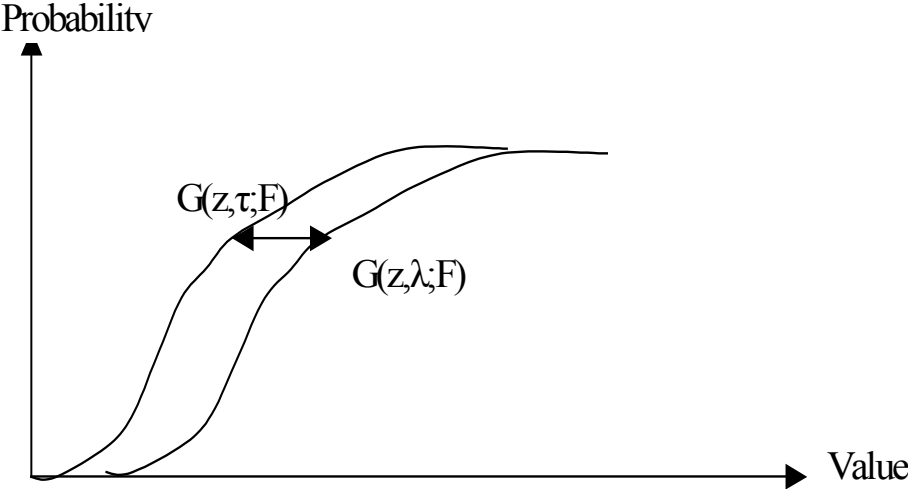


Figure 3.1: First Order Stochastic Dominance of Composite Index λ over the Index τ .

The objective function that we use is the following:

$$\underset{z, \lambda}{Max}[G(z, \boldsymbol{\tau}; F) - G(z, \boldsymbol{\lambda}; F)]$$

The above maximization results in the best-case scenario (most optimistic) hybrid index λ constructed from the set of components in the sense that it reaches the highest level of measured human development for a given probability, implying that the number of observations having a relative development level above a given argument z is maximized.

It is worth mentioning that SD is considerably more general than mean-variance analysis which only looks at the first two moments of the two distributions under comparison. The latter only looks into a dominant relation with a higher mean and lower variance, whereas the former considers all possible moments. Only in the case where we compare two normal distributions does SD reduce to mean-variance analysis. This is also true for PCA which is based on the consideration of the second moment alone after standardizing for a common mean. However, the assumption of normality for each component is difficult to support empirically. In contrast, SD analysis takes into account the whole distribution, not only the mean and the variance. Hence, we could expect significant differences between the SD efficient index and the mean-variance efficient index when more realistic assumptions are made concerning the distributions of the different components. SD is attractive because it is effectively nonparametric as no explicit specification of a utility function or probability distribution functional form is required. In addition, the entire probability density function is taken into account rather than a finite number of moments so it can be considered less restrictive and more robust.

When studying welfare measures, certain criteria need to be satisfied. The SD1 criterion corresponds to all types of utility functions as long as they are non-decreasing in development levels. SD1 only relies on the fact that people are rational in the sense that they prefer more rather than less development (also known as the monotonicity axiom). In other words, a sensible aggregate welfare measure should be increasing in any indicator which is increasing in a social ‘good’, and decreasing in any indicator which represents a social ‘bad’. Accordingly, for aggregate welfare indices containing only social ‘good’ indicators, one hybrid outcome as expressed by the index λ should be ranked higher than that of another hybrid outcome expressed by the index τ if at least one country is better off in λ than in τ , and no one is worse off. So, SD1 of τ by λ means that λ corresponds to a higher measured relative welfare than τ .

When there is no hybrid index λ that dominates the given index τ at first-order, we move

to the SD2 criterion. The objective function that we use is the following:

$$\text{Max}_{z,\lambda} \int_{-\infty}^z G(u, \tau; F) du - \int_{-\infty}^z G(u, \lambda; F) du$$

This maximization results in the most optimistic hybrid index λ constructed from the set of components in the sense that it also gives the greatest value of human development for a given probability.

We can further define for $z \in R$:

$$\begin{aligned} \mathcal{J}_1(z, \boldsymbol{\lambda}; F) &:= G(z, \boldsymbol{\lambda}; F), \\ \mathcal{J}_2(z, \boldsymbol{\lambda}; F) &:= \int_{-\infty}^z G(u, \boldsymbol{\lambda}; F) du = \int_{-\infty}^z \mathcal{J}_1(u, \boldsymbol{\lambda}; F) du, \\ \mathcal{J}_3(z, \boldsymbol{\lambda}; F) &:= \int_{-\infty}^z \int_{-\infty}^u G(v, \boldsymbol{\lambda}; F) dv du = \int_{-\infty}^z \mathcal{J}_2(u, \boldsymbol{\lambda}; F) du, \end{aligned}$$

and so on.

From Davidson and Duclos (2000) Equation (2), we know that

$$\mathcal{J}_j(z, \boldsymbol{\lambda}; F) = \int_{-\infty}^z \frac{1}{(j-1)!} (z-u)^{j-1} dG(u, \boldsymbol{\lambda}, F),$$

which can be rewritten as

$$\mathcal{J}_j(z, \boldsymbol{\lambda}; F) = \int_{\mathbb{R}^n} \frac{1}{(j-1)!} (z - \boldsymbol{\lambda}'\mathbf{u})^{j-1} \mathbb{I}\{\boldsymbol{\lambda}'\mathbf{u} \leq z\} dF(\mathbf{u}).$$

The general hypotheses for testing SD efficiency of order j of τ , hereafter *SDJ*, can be written compactly as:

$$\begin{aligned} H_0^j &: \mathcal{J}_j(z, \boldsymbol{\tau}; F) \leq \mathcal{J}_j(z, \boldsymbol{\lambda}; F) \text{ for all } z \in \mathbb{R} \text{ and for all } \boldsymbol{\lambda} \in \mathbb{L}, \\ H_1^j &: \mathcal{J}_j(z, \boldsymbol{\tau}; F) > \mathcal{J}_j(z, \boldsymbol{\lambda}; F) \text{ for some } z \in \mathbb{R} \text{ or for some } \boldsymbol{\lambda} \in \mathbb{L}. \end{aligned}$$

Under the null Hypothesis H_0^j there is no hybrid index λ constructed from the set of components that dominates the index τ at order j . In this case, the function $\mathcal{J}_j(z, \tau; F)$ is always lower than the function $\mathcal{J}_j(z, \lambda; F)$ for all possible hybrid indices λ for any argument z . Under the alternative hypothesis H_1^j , we can construct a hybrid index λ that for some arguments z , the function $\mathcal{J}_j(z, \tau; F)$ is greater than the function $\mathcal{J}_j(z, \lambda; F)$. Thus, the index τ is SD1 inefficient if and only if some other hybrid index λ dominates it. Alternatively, index τ is SD1 efficient if and only if there is no hybrid index λ that dominates it.

In particular we obtain SD1 and SD2 when $j = 1$ and $j = 2$, respectively. The hypothesis for testing SD of order j of the distribution of index τ over the distribution of index λ takes analogous forms, but for a given λ instead of several of them.

In what follows we will consider how to test for SD of a single composite index over time. We will then proceed to obtain the test statistic for testing for SDE of the equally-weighted HDI.

3.2 Tests for SD of a single composite index over time

In subsection 3.3 below we will present the test statistic for the SD efficiency of the HDI. Before we do that, our objective is to examine the stochastic dominance of the HDI over a twenty-five year period and determine which factors drive its improvement over time. In this case we have a pair-wise comparison of a given index over two points in time, such as the equally-weighted HDI, τ , in year 1975 and in year 1980. We define $G(z, \boldsymbol{\tau}; F)$ the *cdf* of the index at point z given by $G(z, \boldsymbol{\tau}; F) := \int_{\mathbb{R}} \mathbb{I}\{\boldsymbol{\tau}'u \leq z\}dF(u)$.

We focus on a situation in which we have (possibly) dependent samples of indices from two populations (such as a group of countries at two different points in time) that have associated cumulative distribution functions (*cdf's*) given by G and F , and the functions $\mathcal{J}_j(z, \boldsymbol{\tau}; G)$ and $\mathcal{J}_j(z, \boldsymbol{\tau}; F)$. In this context, SD1 of G over F corresponds to $\mathcal{J}_1(z, \boldsymbol{\tau}; G) \leq \mathcal{J}_1(z, \boldsymbol{\tau}; F)$ or $G(z, \boldsymbol{\tau}; G) \leq G(z, \boldsymbol{\tau}; F)$ for all z . When this occurs social welfare in the population summarized by G is at least as large as that in the F population, when U is any increasing monotonic function of z — *i.e.*, $U'(z) \geq 0$. The *cdf* of F is always at least as large as that of G , *i.e.*, distribution F always has more mass in the lower part of distribution.

How is this related to HDI dominance? Suppose we have n countries in total. If the *cdf* of HDI in 1975, $F(z)$, is always at least as large as that of the *cdf* in 1985, $G(z)$ at any point, then the proportion of countries below a particular index level for the year 1975 is higher than that of 1985. Therefore, the 1985 HDI stochastically dominates its 1975 counterpart in the first-order. When the two *cdf* curves intersect, then the ranking is ambiguous. In this situation we cannot state whether one distribution first-order dominates the other. This leads to an ambiguous situation which makes it necessary to use higher-order SD analysis.

SD2 of G over F corresponds to $\mathcal{J}_2(z, \boldsymbol{\tau}; G) \leq \mathcal{J}_2(z, \boldsymbol{\tau}; F)$ for all z and the social welfare in the population summarized by G is at least as large as that in the F population, for any utility function U that is monotonically increasing and concave, that is $U'(z) \geq 0$ and $U''(z) \leq 0$. Second-order stochastic dominance is verified, not by comparing the *cdf's* themselves, but comparing the integrals below them. We examine the area below the $F(z)$ and $G(z)$ curves. Given lower and upper boundary levels, we determine the area beneath the

curves and, if the area beneath the $F(z)$ distribution is larger than the one of $G(z)$, then in this case $G(z)$ stochastically dominates $F(z)$ in the second-order sense. Since we look at the area under the distributions, second-order dominance implies simply an overall improvement and not a point-wise dominance over all the points of the support of one distribution over another.

There is no guarantee that SD2 will hold, so one may want to look for third-order dominance. Third-order stochastic dominance ($SD3$) of G over F corresponds to $\mathcal{J}_3(z, \boldsymbol{\tau}; G) \leq \mathcal{J}_3(z, \boldsymbol{\tau}; F)$ for all z and the social welfare in the population summarized by G is at least as large as that in the F population for any utility function U that satisfies $U'(z) \geq 0$, $U''(z) \leq 0$, and $U'''(z) \geq 0$. This is the case of third-order stochastic dominance and it is equivalent to imposing the condition that it places a higher weight on lower levels of indices.

The general hypotheses for testing SD of the index over time of order j can be written compactly as:

$$\begin{aligned} H_0^j &: \mathcal{J}_j(z, \boldsymbol{\tau}; G) \leq \mathcal{J}_j(z, \boldsymbol{\tau}; F) \text{ for all } z \in [0, \bar{z}], \\ H_1^j &: \mathcal{J}_j(z, \boldsymbol{\tau}; G) > \mathcal{J}_j(z, \boldsymbol{\tau}; F) \text{ for some } z \in [0, \bar{z}]. \end{aligned}$$

Stochastic dominance of any order of G over F implies that G is no larger than F at any point. In this case there is an improvement of the index over time. Thus, if the HDI in 1980 dominates the HDI in 1975, then there is an improvement in the measured development level of each country over time. The alternative hypothesis is the converse of the null and implies that there is at least some index value at which G (or its integral) is strictly larger than F (or its integral). In other words SD fails at some point for G over F . In this case, there can be improvements in development levels for some countries and no improvement or even deterioration of development levels for some other countries over time. Hence, there is no general improvement for all countries simultaneously over time.

3.2.1 Test Statistics

We consider two time-dependent samples from two distributions (e.g., for HDI in 1975 and 1980). In order to allow for different sample sizes we need to make assumptions about the way in which sample sizes grow.

Assumption 1:

(i) $\{X_i\}_{i=1}^N$ and $\{Y_i\}_{i=1}^M$ are independent random samples from distributions with CDF 's F and G respectively;

(ii) the sampling scheme is such that as $N, M \rightarrow \infty$, $\frac{N}{N+M} = \phi$ where $0 < \phi < 1$.

Assumption1(i) deals with the sampling scheme and would be satisfied if one has samples

of indices from different segments of a population or separate samples across time. Assumption 1(ii) implies that the ratio of the sample sizes is finite and bounded away from zero.

The empirical distributions used to construct the tests are respectively,

$$\widehat{F}_N(z) = \frac{1}{N} \sum_{i=1}^N \mathbb{I}(X_i \leq z), \quad \widehat{G}_M(z) = \frac{1}{M} \sum_{i=1}^M \mathbb{I}(Y_i \leq z).$$

The test statistics for testing the hypotheses can be written compactly as follows:

$$\widehat{S}_j = \left(\frac{NM}{N+M} \right)^{1/2} \sup_z (\zeta_j(z; \widehat{G}_M) - (\zeta_j(z; \widehat{F}_N)).$$

Since ζ_j is a linear operator, then

$$\zeta_j(z; \widehat{F}_N) = \frac{1}{N} \sum_{i=1}^N \zeta_j(z; \mathbb{I}_{X_i}) = \frac{1}{N} \sum_{i=1}^N \frac{1}{(j-1)!} \mathbb{I}(X_i \leq z) (z - X_i)^{j-1} \quad (3.1)$$

where \mathbb{I}_{X_i} denotes the indicator function $\mathbb{I}(X_i \leq x)$ (Davidson and Duclos 2000).

The asymptotic properties of the tests are gathered in appendix A. We consider tests based on the decision rule:

reject H_0^j if $\widehat{S}_j > c_j$

where c_j are suitably chosen critical values to be obtained by simulation methods.

In order to make the result operational, we need to find an appropriate critical value c_j to satisfy $P(\overline{S}_j^F > c_j) \equiv \alpha$ or $P(\overline{S}_j^{G,F} > c_j) \equiv \alpha$ (some desired probability level such as 0.05 or 0.01). Since the distribution of the test statistic depends on the underlying distribution, we rely on bootstrap methods to simulate the p-values. We discuss these methods in appendix D1.

3.3 Tests of the SD efficiency of the HDI

In the previous section, we discussed stochastic dominance tests of HDI and each separate sub-index over time by considering a pair-wise comparison of a given index over two points in time. In this section, we derive statistics to test for SD efficiency of the official HDI, τ , i.e., equal weights given to each sub-index, with respect to all possible combinations of weighting schemes (λ) constructed from the given set of components.

$$\mathcal{J}_j(z, \lambda; \widehat{F}) = \frac{1}{T} \sum_{t=1}^T \frac{1}{(j-1)!} (z - \lambda' \mathbf{Y}_t)^{j-1} \mathbb{I}\{\lambda' \mathbf{Y}_t \leq z\},$$

This can be rewritten more compactly for $j \geq 2$ as:

$$\mathcal{J}_j(z, \boldsymbol{\lambda}; \hat{F}) = \frac{1}{T} \sum_{t=1}^T \frac{1}{(j-1)!} (z - \boldsymbol{\lambda}' \mathbf{Y}_t)_+^{j-1}.$$

3.3.1 Test Statistics

We consider the weighted Kolmogorov-Smirnov type test statistic

$$\hat{S} := \sqrt{T} \frac{1}{T} \sup_{z, \boldsymbol{\lambda}} \left[G(z, \boldsymbol{\tau}; \hat{F}) - G(z, \boldsymbol{\lambda}; \hat{F}) \right],$$

and a test based on the decision rule:

$$\text{reject } H_0^j \text{ if } \hat{S}_j > c_j,$$

where c_j is some critical value (see ST, section 2 for the derivation of the test). The asymptotic properties of the test statistic are collected in appendix B. In order to make the result operational, we need to find an appropriate critical value c_j . Since the distribution of the test statistic depends on the underlying distribution, we rely on a block bootstrap method to simulate p-values. We discuss how to obtain simulated p-values for dependent data using bootstrapping methods in appendix D2.

4 Mathematical formulation of the test statistics for SD1

Testing for SD1 is based on the following test statistic \hat{S}_1 , derived using mixed integer programming formulations. The full formulation of the testing problem is given below:

$$\max_{z, \boldsymbol{\lambda}} \hat{S}_1 = \sqrt{T} \frac{1}{T} \sum_{t=1}^T (L_t - W_t) \tag{4.1a}$$

$$\text{s.t. } M(L_t - 1) \leq z - \boldsymbol{\tau}' \mathbf{Y}_t \leq M L_t, \quad \forall t \tag{4.1b}$$

$$M(W_t - 1) \leq z - \boldsymbol{\lambda}' \mathbf{Y}_t \leq M W_t, \quad \forall t \tag{4.1c}$$

$$\mathbf{e}' \boldsymbol{\lambda} = 1, \tag{4.1d}$$

$$\boldsymbol{\lambda} \geq 0, \tag{4.1e}$$

$$W_t \in \{0, 1\}, L_t \in \{0, 1\}, \quad \forall t \tag{4.1f}$$

with M being a large constant.

The model is a mixed integer program maximizing the distance between the sum over all scenarios of two binary variables, $\frac{1}{T} \sum_{t=1}^T L_t$ and $\frac{1}{T} \sum_{t=1}^T W_t$ which represent $G(z, \boldsymbol{\tau}; \hat{F})$ and $G(z, \boldsymbol{\lambda}; \hat{F})$, respectively (the empirical cdf of $\boldsymbol{\tau}$ and $\boldsymbol{\lambda}$ at point z). According to inequalities (4.1b), L_t equals 1 for each scenario $t \in T$ for which $z \geq \boldsymbol{\tau}'\mathbf{Y}_t$, and 0 otherwise. Analogously, inequalities (4.1c) ensure that W_t equals 1 for each scenario for which $z \geq \boldsymbol{\lambda}'\mathbf{Y}_t$. Equation (4.1d) defines the sum of all index weights to be unity, while inequality (4.1e) disallows negative weights. This formulation allows for a test of the dominance of the equally-weighted HDI, τ , over any potential linear combination $\boldsymbol{\lambda}$ of the components. When some of the variables are binary, corresponding to mixed integer programming, the problem becomes NP-complete (non-polynomial, i.e., formally intractable).

We can see that there is a set of at most T values, say $\mathcal{R} = \{r_1, r_2, \dots, r_T\}$, containing the optimal value of the variable z . A direct consequence is that we can solve the original problem by solving the smaller problems $P(r)$, $r \in \mathcal{R}$, in which z is fixed to r . Then we take the value for z that yields the best total result. The advantage is that the optimal values of the L_t variables are known in $P(r)$.

The reduced form of the problem is as follows (see appendix E1 for the derivation of this formulation and details on its practical implementation)

$$\begin{aligned}
& \min \sum_{t=1}^T W_t \\
& \text{s.t. } \boldsymbol{\lambda}'\mathbf{Y}_t \geq r - (r - M_t)W_t, \quad \forall t \in T \\
& \quad \mathbf{e}'\boldsymbol{\lambda} = 1, \\
& \quad \boldsymbol{\lambda} \geq 0, \\
& \quad W_t \in \{0, 1\}, \quad \forall t \in T.
\end{aligned} \tag{4.2a}$$

A similar procedure is used in the formulation of the test statistic for SD2. The exact formulation for testing for SD2 is presented in appendix E2.

We derived statistics to test for SD efficiency of the official HDI (i.e., each sub-index being equally weighted) with respect to all possible combinations of weighting schemes constructed from the set of components. In the next section, before moving to the empirical analysis of HDI, we present some simulation experiments to evaluate the importance of different distributional component characteristics in the derivation of best-case scenario optimistic

weights.

5 Simulation Experiments

We present simulation results for three different experiments. In each case we have three different components (as in the case of HDI) all normally distributed that are used to construct the equally-weighted composite index using 500 observations. The results are reported in Table 1.

In the first experiment, we simulate three components which are normally distributed with each component having the same mean, 0.5, and same variance, 0.1 and we construct an equally-weighted composite index from these simulated components. The results of the first panel of Table 1 show that there is no case that dominates the equally-weighted composite index and there are 164 cases which have the same efficiency as the equally-weighted index.

In the second case, we simulate three normally distributed components with the same mean, 0.5. However we allow for different component variances, 0.15, 0.1 and 0.05 respectively, something that would enable us to see directly the effect of variability on the construction of the composite index. The results in the second panel of Table 1 show that there are 203 composite indices for a given “ z ” point that dominate the equally-weighted composite index and it is clear that the least variable component has the greatest impact. In that case, the least variable component’s weight (the third component) from these 203 dominant indices is on average 0.6589. On the other hand the second and third least variable components with respective variances 0.1 and 0.15 have weights 0.2589 and 0.0822 respectively. The above simulation results suggest that using the fixed equal weighting scheme will result in an index that is dominated by many other potential hybrids with different weights. One can see that when the means of each component are the same, the least variable component has the greatest impact on the construction of the most optimistic index.

In the third experiment, we allow the three components to have different mean values, 0.55, 0.5 and 0.45 respectively. Given these mean values, we allow for different possible variance (standard deviation) combinations, where each component takes a different standard deviation value in each case from a set of $\{0.05, 0.1, 0.15\}$. The results of the third panel show that other things being equal, the component with the highest mean has more impact and gets more weight (as in the 1st row where the first component gets a weight of 0.77). However, the weight drops if the component with the highest mean has also the highest variance, as seen in the second row where the average weight falls to 0.70 from 0.77. There is an offsetting effect as a higher mean implies a higher weight, whereas the opposite is true

for a higher variance (higher variability).

Overall, we find that when all components have the same mean and the same standard deviation, the equally-weighted composite index is efficient and there is no hybrid index that dominates it. On the other hand, when each component has the same mean and different standard deviations, then the least variable component has the greatest impact on the construction of the most optimistic index. When each component has a different mean and the same standard deviation, then the component with the higher mean has the greatest impact. When both mean and standard deviations vary, then the component with the highest mean and the lowest variability relative to the other components has the greatest impact on the construction of the best-case scenario index. There is a trade off between mean and variance and in the case where one component has the highest mean and highest standard deviation and the other component has the second highest mean but is less variable, then both components would have almost an equal impact on the construction of the most optimistic index.

5.1 Data augmentation with heterogeneous new entrants

In order to check the robustness of the simulation results presented in Table 1, we will investigate whether these will change when we add countries (observations) with different characteristics. Taking as given the means and standard deviations of the existing data series (the three components have mean values of 0.55, 0.5 and 0.45 respectively and the same standard deviation 0.1) we allow for 100 more observations to be added to the existing data. The results are presented in the fourth panel of Table 1.

In the first experiment, the 100 new entrants of the second and third components have the same mean values of 0.5 and 0.45 respectively and the same standard deviations of 0.1 as before. However, the statistical characteristics of the first component are different than before for these additional 100 new entrants, with a mean of 0.6, and different variance (standard deviation) combinations, $\{0.05, 0.1, 0.15\}$. We observe that the weights do not vary significantly when these new observations (new countries) with different characteristics enter into the simulation experiment. At the first row, we observe that the changes of weights to each component are -0.0074, 0.0064 and 0.0010 respectively. As the overall mean of the first component increases, its weight increases slightly without changing much the nature of the previous results. We observe that the largest change in the components' weights is only about 2%.

In the second experiment, the 100 new entrants of the first and third components have the same mean values of 0.55 and 0.45 respectively and the same standard deviations 0.1, but

the statistical characteristics of the second component are different from before for the 100 new entrants, with a mean of 0.6 and different variance (standard deviation) combinations, {0.05, 0.1, 0.15}. Again, the weights do not vary significantly when new countries with different characteristics enter into the simulation experiment. Since the mean of the second component is now greater, its weight now slightly increases. Even in this case the largest change in the components' weights is only about 3%.

In the third experiment, the 100 new entrants of the first and second components have the same mean values of 0.55 and 0.5 respectively, and the same standard deviations 0.1, but the statistical characteristics of the third component are different from before for the 100 new entrants, with a mean of 0.6 and a standard deviation that takes values from the set {0.05, 0.1, 0.15}. Since the mean of the third component is now greater, there is a small increase in its weight. In this case also the largest change in the weights is only about 2.5%.

Overall, we observe that the entrance of new (observations) countries with different statistical characteristics will result in a 2% to 3% change in the relative weights attached to the individual components. We found that even though the number of observations increased by 20% with 100 new entrants, the change in the resulting weighting scheme is minor. Since we have a total of 1264 observations in the existing HDI data set, we anticipate that any new additions to the HDI data set that may occur in one of the following 5-year periods will be of a smaller magnitude than that, with expected weight changes being less than 2%.¹¹

In the above experiments we observe the role of the mean in arriving at these weights. The SD approach maximizes the distributional distance between the given (equally-weighted) index and any possible alternative. In comparing distributions, we know that the mean plays the key role, followed by variability. The mean indicates the achievement level offered by each component, while the standard deviation shows the variability of the achievement. The most optimistic index obtained from the stochastic dominance approach is the one that measures the greatest achievement over time, the greatest measured development level, and at the same time exhibits discernibly the most stable performance.

In this section, we examined the importance of component statistics to derive the most optimistic weights. In the following section, we will proceed with the application of SD analysis to the HDI data. We will first present the descriptive statistics of HDI and its components followed by the SD analysis of each component over time and the derivation of the most optimistic weights.

¹¹We also repeated without reporting the same procedure by adding 50 and 25 new entries respectively (10% and 5% of the existing data set). In all cases, the changes in the relative weighting scheme are minor, less than 2% for each component.

6 Empirical Analysis of SD efficiency of HDI

6.1 Data and Descriptive Statistics

We use the United Nations Development Program's HDI and its components - life expectancy, education and GDP indices for the period 1975 to 2000 in 5-year increments. Each index ranges between 0 and 1 (from lowest to highest well being). The HDI represents the simple arithmetic average of the three individual indices.

The definition of the life expectancy index (LE) is given by $LE = \frac{LE-25}{85-25}$. The life expectancy raw data series has an upper bound of 85 and a lower bound of 25 years. The value of a country's life expectancy index is obtained by the country's life expectancy in years minus 25 divided by 60, for a number that would lie between 0 and 1. The education index (E) is defined as $E = \frac{2}{3}(\text{adult literacy index}) + \frac{1}{3}(\text{gross enrollment index})$. This index is constructed so that a 2/3 weight is given to literacy (percentage of the population that is considered literate) and a 1/3 weight is given to gross school enrollment as a percentage of the eligible school age population and it is bounded between 0 and 1. Finally, the GDP per capita index is defined as, $GDP\ Index = \frac{\log(\text{GDP per capita}) - \log(100)}{\log(40000) - \log(100)}$. It is created in a similar manner as LE, where the upper bound for the raw GDP per capita series is 40000 and the lower bound is 100 US dollars per capita. The values taken by the index lie in the (0,1) range. Each separate index is then equally weighted to create the HDI.¹²

Table 2 presents the descriptive statistics for HDI and the individual component indices over time. It is evident that HDI improved over time, as did LE and E, whereas the GDP per capita index remained almost unchanged between 1980 and 1995, while it fell in the period from 1980 to 1985. We see that E increased significantly over this time period, while LE remained steady after 1990. This is mainly because of the fall in life expectancy in Africa. It appears that education has the largest mean among the components, whereas all three have similar standard deviations. Given the simulation results of the previous section, the descriptive statistics suggest that education would be the dominant component of the best-case scenario index based on SDE testing, something that we will verify below.¹³ In

¹²Starting from 2010, the UNDP made adjustments to how the HDI is constructed. Not only the definitions of some components but also the upper and lower bounds of the raw components have changed. The component indices of HDI after the year 2010 are calculated as: Income index (II): $\frac{\ln(\text{GNI per capita}) - \ln(163)}{\ln(108211) - \ln(163)}$. Education index (EI) = $\frac{\sqrt{MYS \cdot EYS}}{0.951}$ where mean years of schooling (MYS) index = $\frac{MYS-0}{13.2-0}$ and Expected years of schooling (EYS) index = $\frac{EYS-0}{20.6-0}$. Life expectancy index (LEI): $\frac{LE-20}{83.2-20}$. Finally, HDI is obtained by the geometric mean of the those three indices: $\sqrt[3]{II \cdot EI \cdot LEI}$.

¹³Even if we standardize using the means and variances for each index, each index's empirical distribution will remain the same. In that case, for example, the education index will continue to be negatively skewed and most of the outcomes will be greater than the standardized zero mean.

the next section we will examine the SD dominance results for these indices separately to establish the dominant component that drives the HDI improvements over time.

6.2 Results for SD tests

We will discuss the results of Kolmogorov-Smirnov tests for HDI and its components separately. Table 3 presents the results for SD1 and SD2 over the period under investigation based on bootstrap methods from BD for stochastic dominance with dependent data. For completeness, in Table 4, we also apply the Linton et al. (2005) subsampling approach to HDI and its components to compare the findings with the BD sampling approach. We first test whether the HDI in 1980 dominates the HDI in 1975, and separately we test whether each individual component (e.g., education) in 1980 dominates this component in 1975 in order to establish whether over time improvements have occurred and in addition, which component is mainly responsible for such improvements. The vertical column of Table 3 represents the years from 1980 to 2000 that are tested for stochastic dominance against years from 1975 to 1995. Percentage levels in the table represent the significance level of stochastic dominance (e.g., in the first panel of Table 3: 1980 year HDI stochastically dominates the 1975 year in the second-order sense at the 10 percent level). N/A means that there is no dominance at that order.¹⁴

The results in Table 3 suggest that there is no improvement for any index using a 5 year testing horizon. In all such cases SD1 is rejected. However, apart from the GDP index, all other indices display significant improvements using a 10 year horizon. In almost all 10 year or greater periods, there is dominance at first-order at the 1% significant level, for education and life expectancy, although not as strong for the latter as for the former. The exception is the GDP index, where as seen in the fourth panel of Table 3, there are no discernible significant improvements over the whole period.

It becomes apparent that the improvements in the HDI over time are driven by the improvement in education and life expectancy. However, the improvement in education index occurs even in 5-year periods in a second-order sense, something that implies that education may be improving more rapidly over shorter time periods.

We proceed to use the Linton et al. (2005) subsampling approach to HDI and its components in order to compare its findings with those of the BD bootstrapping approach presented in Table 3. The same number of countries is used to test if there are first and second-order

Therefore, even if we standardize each index, we will get exactly the same results as before.

¹⁴We first test for SD1: if there is dominance at first-order, then there will be dominance at any other greater order. If not, then we continue for SD2.

of dominance over time for each component of HDI. Table 4 presents the results for SD1 and SD2 for HDI and its components respectively. The null hypothesis is that the respective index in the following years dominates the index of the previous years and we report p-values for SD1 and SD2. We observe that in general, the null hypothesis is not rejected, suggesting the presence of an overall improvement over time for all indices. The only exception is that we reject the null hypothesis that the 1990 life expectancy dominates 1985 life expectancy at any order. The same is true for the period 1990 to 2000.

There are some differences between the BD and the Linton et al. (2005) results. The most striking one is that the GDP per capita index has shown an improvement over time when we use the latter approach as opposed to the former. There are two main reasons for this. The first one is that for the BD approach we allow for an unbalanced panel, as a different number of countries can be examined over time. This is not the case for the Linton et al. (2005) approach that requires a balanced, and as a result a more homogeneous, panel for its analysis. The second reason is that the null hypothesis in the BD approach excludes equality from dominance, whereas it is included in the null hypothesis of Linton et al. (2005). In that case, there may be under-rejection of dominance over time as there could be many equal outcomes that would favour dominance.

In this section, we applied SD analysis over time to each component sub-index in order to establish the dominant one responsible for the overall improvement of HDI over time. The SD tests were conducted using pair-wise comparisons for each separate sub-index over time, without allowing for differential weights for each component. In the next section, we will allow for full diversification of weights to test whether assigning equal weights to each sub-index leads to the most optimistic view or whether alternative weighting schemes imply higher relative development levels and less variability across countries and over time.

6.3 SDE Results for HDI

We continue with our findings of the test for SD1 efficiency of the HDI. We found that the equally-weighted HDI does not offer the best-case scenario. We can construct many other hybrid composites λ consisting of the three components of the HDI (life expectancy, educational attainment, and GDP per capita) that stochastically dominate the equally-weighted HDI, τ , in the first-order sense (e.g., for which $G(z, \tau; F) > G(z, \lambda; F)$). There are 293 different such composite λ 's. Table 5 summarizes the results. This table presents the average weights of the 293 hybrid composites that dominate the standard HDI. It is clear that education has the greatest impact with a 71.17% (0.7117) weight. On the other hand, life expectancy and GDP per capita take weights of 12.38% (0.1238) and 16.45% (0.1645)

respectively. The inefficiency of the official HDI indicates that the equal weighting scheme achieves lower levels of measured development as there are alternative weighting schemes that assign a higher measured development level to each country. SDE analysis allows us to derive the most optimistic weighting scheme where more countries achieve higher measured development levels and less variability both cross-sectionally and over time. Furthermore, the weights derived from SDE analysis can be thought of as explicit weights that lead to the most optimistic development scenario, where the emphasis is placed on educational improvements. The empirical findings confirm the simulation results of the previous section. Education is the dominant constituent component of the most optimistic index as it dominates in terms of mean the other two (even though in terms of variance all three components are quite similar). In this case, education is the key factor that leads to the best-case development scenario, where higher and more stable relative measured levels of development are achieved cross-sectionally and over time.

We also conducted some additional robustness analysis. We allowed for the possibility that the importance of education in the construction of the most optimistic scenario of the HDI changes as we move to a more qualitative measure of education. Education attainment in the HDI consists of a country's adult literacy rate and gross enrollment rate which represent quantitative measures of a given country's educational level. We repeated the analysis using data that capture the quality of educational attainment only as well a combination of both quality and quantity. As measures of quality of education we considered data from the Trends in International Mathematics and Science Study (TIMSS), from the Programme for International Student Assessment (PISA) and from the Progress in International Reading Literacy Study (PIRLS). However, the data set on the quality of education is limited, since these data were first collected only in the mid-1990s. The Trends in International Mathematics and Science Study (TIMSS) conducted tests in mathematics and science to test the achievements for fourth- and eighth-grade students for each of the participating countries in 1995, 1999, 2003, 2007 and 2011. The Programme for International Student Assessment (PISA) implemented tests for science, mathematics and reading achievements of students in 2000, 2003, 2006 and 2009. Lastly, Progress in International Reading Literacy Study (PIRLS) had a literacy assessment in 2001, 2006 and 2011. Since we have data for HDI until 2003, we have coverage by the TIMSS for the three years 1995, 1999 and 2003, the PIRLS assessment for year 2001 and the PISA assessment for 2000. Therefore, we have quality of education data for the years 1995, 1999, 2000, 2001 and 2003 with a total of 160 observations. The number of countries covered in each of these years are 38, 29, 25, 29 and 39 respectively. Each country's science, mathematics and reading achievement is scaled to lie between zero

and one.¹⁵

We test three different cases and we combine the results. In the first case we have 160 observations using data that represent the quantitative aspect of education (as in the original HDI), life expectancy and the GDP index to test whether the standard HDI offers the best-case scenario. In the second case, we replace the education index by the quality of education index and obtain an adjusted HDI by giving equal weights to each index (i.e., life expectancy and the GDP index remain the same, but the education index is replaced by the quality of education index). We then test whether this HDI offers the most optimistic view. Finally, in the third case, we combine the quality and quantity of education indices by giving equal weight to each component. We obtain an equally-weighted HDI for this case and we test whether it is the best-case scenario with respect to SD1 efficiency. Overall, regardless of the way education is measured, it has the greatest impact on the construction of the most optimistic view of HDI. The impact of education is the lowest (80.04%) when the quality of education index is used, while it is highest (86.29%) when the quantity of education is used.¹⁶

Next, we will present country rankings for the years 1995, 2000 and 2006 using the most optimistic view of HDI that resulted from the stochastic dominance tests (e.g., with weights 71.17% for education, 12.38% for life expectancy and 16.45% for GDP per capita) and the equally-weighted standard HDI.¹⁷ The first panel of Table 6 presents the rankings of the top twenty countries using both the best-case scenario and the standard HDI for years 1995, 2000 and 2006. For example for 2006, we observe that Sweden, Japan, and Switzerland moved out of the top 10 group under the equally-weighted HDI and they were replaced by Finland, Denmark and New Zealand in the new ranking. Iceland, Ireland and Netherlands remained in the top ten group of countries moving however to a lower ranking position. Australia moved to a higher ranking, Norway remained at the second position, while Canada now moved to the highest spot.

The second panel of Table 6 reports the twenty countries that moved to a higher ranking position in years 1995, 2000 and 2006 under the most optimistic view of HDI relative to the standard HDI (e.g., for 2006, Guyana ranked at the 110th position under the standard HDI

¹⁵The scaling is done using the achievement of a country at a given year divided by the maximum achievement for that given year.

¹⁶The average weights of education are now higher, since the data set for the quality of education is limited, with 160 observations confined only to the set of developed and more homogeneous countries. The results are available upon request from the authors.

¹⁷It is worth noting that the new ranking is highly correlated with the original ranking. The Spearman correlation between the old and new ranking is 0.95. This is to be expected since all the original components are highly correlated and the composite indices are constructed as weighted averages of these components.

moved to the 73rd position under the best-case scenario of the HDI, an improvement in its ranking of 37 positions). The main reason that these countries moved to a higher ranking under the most optimistic view of the HDI is that most of them, such as Ukraine, Kazakhstan, Kyrgyzstan, Belarus, Turkmenistan and Russia were part of the Soviet Union that had a good educational system, even though GDP per capita was relatively low. Furthermore, the large upward ranking changes occur because these countries are the ones experiencing bad outcomes not only in their GDP per capita but also in life expectancy. In that case, equally weighting each index would understate these countries' achievement at the educational level.

In the third panel of Table 6 we report the twenty countries that moved to a lower ranking position under the most optimistic view of the HDI relative to the standard HDI in years 1995, 2000 and 2006. For example for 2006, Oman ranked at the 53rd position with the equally-weighted index moved to be 101st under the best-case scenario optimistic index, a deterioration of 48 positions. The main reason that these countries moved to a lower ranking is that they have relatively higher GDP per capita, as most of them are resource-dependent economies (oil producers), with relatively fewer resources allocated to education. As a result, their educational achievements lag behind those of other countries. We should note that a resource-dependent country could still invest in education if the country has a social structure that allows its citizens to access resources equally and/or redistribute its achievement in one attribute (i.e., standard of living) through fostering other dimensions (i.e., life expectancy and education). Therefore, we further analyze the raw components of the education index for those countries that moved to a lower ranking. One of the main factors behind the weakness of their educational system appears to be high gender inequality (i.e., low female participation in the educational system).¹⁸

We proceed to examine the improvement in the relative levels of human development when the most optimistic weighting scheme is used. In this context, we address the following question: "If we weight the components to arrive at the most optimistic view of human development, across countries and in earlier time periods, then to what extent has there been

¹⁸In 1995, 16 out of 20 countries experienced a high gender inequality in adult literacy rates. For example, percentages of literacy rates are 46% and 71% for female and male respectively in Oman. Similarly, for Saudi Arabia (50.3% and 71.5%), for Kuwait (74.9% and 82.2%), for Algeria (49.1% and 73.9%), for Turkey (72.4% and 91.7%), for Iran (59.3% and 77.7%), for Tunisia (54.6% and 78.6%), for Syria (55.8% and 85.7%), for Malaysia (78.1% and 89.1%), for Singapore (86.3% and 95.9%), for Hong Kong (88.2% and 96%), for Mauritius (78.8% and 87.1%), for Egypt (38.8% and 63.3%), for Morocco (31% and 56.6%), for Guatemala (57.2% and 72.8%) and for Botswana (59.9% and 80.5%) respectively for female and male literacy rates. It is also worth mentioning that for Luxembourg, Singapore and Hong Kong, even though literacy rates are very high, their gross enrollment ratios are around 60-70% as the majority of the population from those countries leave to pursue higher education in other countries.

a general improvement over time under this best-case scenario?” In order to examine the improvement in human development over time, we compare the percentages of countries that fall into different human development groups (i.e., low, medium, high and very high human development groups) using the official HDI with that using the optimistic weighting scheme for the years 1995, 2000 and 2006. The UNDP’s Human Development Report separates countries into low, medium, high and very high human development groups where each group consist of countries that have HDI values less than 0.5, between 0.5 and 0.799, between 0.8 and 0.899, and above 0.9 respectively.

The first panel of the Table 7 presents the percentage of countries in each human development group with the official HDI in 1995, 2000 and 2006, whereas the second panel of the Table 7 offers the same information for the best-case scenario case. Over time, there would always have been a lower percentage of countries in the low and medium human development groups and a higher percentage of countries in the high and very high human development groups with the most optimistic case than the official HDI. With both the official HDI and the most optimistic scenario, the percentage of countries in the low development group decreased over time. However, the change in the percentage of countries that fall into the medium, high and very high human development groups does not follow a particular pattern over time with the official HDI. From 1995 to 2000, the percentage of countries in the medium development level group increased (from 38% to 49%), whereas the percentages of countries in both the high and very high development groups decreased (from 22% to 19% and 15% to 12% respectively) with the official HDI. From 2000 to 2006, the percentage of countries in the medium development level group decreased (from 49% to 44%) and both the percentages of countries in the high and very high development groups increased (from 19% to 23% and 12% to 18% respectively) with the official HDI. On the other hand, with the optimistic scenario case, there is a distinct improvement over time. Both the percentages of countries in the low and medium human development groups decreased over time, while the percentages of countries in both the high and very high human development groups increased. For the 1995 to 2006 period, a percentage of countries moved from the low to the medium development group but there have been even more countries that moved from the medium to the high and very high human development groups. In 2006, almost 60% of the countries were categorized in the high and very high development groups with the optimistic scenario case, while there were around 40% of the countries in the high and very high development groups with the official HDI.

Overall, we observe that when we change the weighting scheme in the construction of HDI, the ranking of countries will change. Although it has been suggested that weighting

each index differently should not change the ranking when the correlation is high among the constituent indices (as is here the case), the SD approach demonstrates that weighting each index differently does have an impact on outcomes.¹⁹

7 Conclusion

In this paper we employ consistent SD tests to examine whether there has been a general improvement in the official HDI and its components over time. The results suggest that there is no general improvement for any index using a five-year testing horizon (subperiods within 1975 to 2000). However, apart from the GDP index, all other indices display significant improvements using a ten-year horizon. In almost all ten year or greater periods, there is a general improvement in education and life expectancy, although not as strong for the latter as for the former. Moreover, there is no general improvement in the life expectancy index between the period 1990 and 2000. For the GDP index, there are no discernible significant general improvements over the whole period. In other words, the improvement in the official HDI over-time is mainly driven by improvements in the education index, the fast-responding indicator to its targets. This indicator has shown improvements for all countries within the ten-year horizon periods, whereas life expectancy and the GDP index are the slow-moving indicators holding back the overall improvement in the official HDI.

Moreover, we present tests for SDE of any order for time-dependent data. We apply tests for SDE of a given index with respect to all possible indices constructed from a set of individual components. We proceed to test whether SDE justifies the use of the standard equally-weighted HDI, when compared with any other index constructed with alternative weights for the three constituent components: education, life expectancy and GDP per capita. SDE analysis results in the most optimistic weighting scheme where more countries display higher measured relative development levels and less variability both cross-sectionally and over time. The over-time improvement in the education index sheds light on the other finding of the paper that education is the key factor that leads to a more optimistic view. This result is also confirmed when we use data on the quality of education. In other words, the analysis in the paper suggests that anyone inclined, on prior grounds, to weight education

¹⁹This is the so called redundancy argument of McGillivray (1991), McGillivray and White (1993) and Cahill (2002) who argued that the HDI and/or its components are so closely correlated, that there is a redundancy in terms of informational content in forming the index and as such one of the components would dominate. Both the simple and the Spearman-rank correlation coefficients are very high among the three components (above 0.8) and significant.

more strongly than does the official HDI, would tend to take a more optimistic view of the extent of a general improvement in welfare.

With the best-case scenario weighting scheme we arrive at new country rankings that are quite different from the ones obtained using the standard equally-weighted HDI. The rankings based on SDE are more stable as they are based on a choice of weights that minimizes the variability. Countries that achieve consistently higher levels in each component do not experience dramatic changes. On the one hand, we find that countries with a good education system but with a low standard of living (e.g., countries that were part of the old Soviet Union) move up in the rankings. On the other hand, countries with a higher living standard and/or life expectancy but with a weak education system (e.g., resource-dependent economies) move down in the rankings. High gender inequality (i.e., low female participation in the educational system) seems to be one of the main factors behind the weakness of the educational system in these countries.

The next step in this line of work is to develop estimators of efficiency lines as suggested by Davidson and Duclos (2000) for poverty lines using SD analysis. For the first order we should estimate the lowest development level at which the distribution associated with the HDI under test intersects with the distribution generated by any combination of the components. Similarly we could rely on an intersection between integrals of these distributions to determine efficiency lines at higher orders.

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APPENDIX

A Asymptotic Distributions

The limiting distributions of the test statistics under the null hypothesis can be characterized using the fact that

$$\sqrt{N}(\widehat{F}_N - F) \implies \mathfrak{B}_F \circ F, \quad \sqrt{M}(\widehat{G}_M - G) \implies \mathfrak{B}_G \circ G$$

where $\mathfrak{B}_F \circ F$ and $\mathfrak{B}_G \circ G$ are independent Brownian Bridge processes.

BD obtain the characterizing behavior of the test statistics and derive the asymptotic properties of the process that involves integrals of the Brownian Bridges under their Lemma 1

Lemma 1: BD show that for $j \geq 2$,

$\sqrt{N}(\zeta_j(\cdot; \widehat{F}_N) - \zeta_j(\cdot; F)) \implies \zeta_j(\cdot; \mathfrak{B}_F \circ F)$ in $C([0, \bar{z}])$ where the limit process is with mean zero and covariance kernel given by (for $z_2 \succ z_1$)

$$\begin{aligned} \Omega_j(z_1, z_2, F) &= E(\zeta_j(z_1; \mathfrak{B}_F \circ F)\zeta_j(z_2; \mathfrak{B}_F \circ F)) \\ &= \sum_{l=0}^{j-1} \theta_l^j \frac{1}{l!} (z_2 - z_1)^l \zeta_{2j-l-1}(z_1; F) - \zeta_j(z_1; F)\zeta_j(z_2; F) \end{aligned}$$

where

$$\theta_l^j = \binom{2j-l-2}{j-1}.$$

Note that this process also holds for G . Lemma 1 provides the covariance kernel in terms of the coefficients θ_l^j and the integration operators that is useful in what follows.

We consider tests based on the decision rule:

$$\text{reject } H_0^j \text{ if } \widehat{S}_j \succ c_j$$

where c_j is some critical value that will be discussed in a moment.

The following result characterizes the properties of tests, where

$$\overline{S}_j^F = \sup_z \zeta_j(z; \mathfrak{B}_F \circ F)$$

$$\overline{S}_j^{G,F} = \sup_z (\sqrt{\phi} \zeta_j(z; \mathfrak{B}_G \circ G) - \sqrt{1-\phi} \zeta_j(z; \mathfrak{B}_F \circ F))$$

B Asymptotic distribution

$\sqrt{T}(\widehat{F} - F)$ tends weakly to a mean zero Gaussian process $\mathcal{B} \circ F$ in the space of continuous functions on \mathbb{R}^n (see Rio (2000) for the multivariate functional central limit theorem for stationary strongly mixing sequences). ST derive the limiting behavior using the Continuous Mapping Theorem (as in Lemma 1 of BD).

Lemma B.1 $\sqrt{T}[\mathcal{J}_j(\cdot; \hat{F}) - \mathcal{J}_j(\cdot; F)]$ tends weakly to a Gaussian process $\mathcal{J}_j(\cdot; \mathcal{B} \circ F)$ with mean zero and covariance function given by:

- for $j = 1$:

$$\begin{aligned}\Omega_1(z_1, z_2, \boldsymbol{\lambda}_1, \boldsymbol{\lambda}_2) &:= E[G(z_1, \boldsymbol{\lambda}_1; \mathcal{B} \circ F)G(z_2, \boldsymbol{\lambda}_2; \mathcal{B} \circ F)] \\ &= \sum_{t \in \mathbb{Z}} E[\mathbb{I}\{\boldsymbol{\lambda}'_1 \mathbf{Y}_0 \leq z_1\} \mathbb{I}\{\boldsymbol{\lambda}'_2 \mathbf{Y}_t \leq z_2\}] - G(z_1, \boldsymbol{\lambda}_1; F)G(z_2, \boldsymbol{\lambda}_2; F),\end{aligned}$$

- for $j \geq 2$:

$$\begin{aligned}\Omega_j(z_1, z_2, \boldsymbol{\lambda}_1, \boldsymbol{\lambda}_2) &:= E[\mathcal{J}_j(z_1, \boldsymbol{\lambda}_1; \mathcal{B} \circ F)\mathcal{J}_j(z_2, \boldsymbol{\lambda}_2; \mathcal{B} \circ F)] \\ &= \sum_{t \in \mathbb{Z}} \frac{1}{((j-1)!)^2} E[(z_1 - \boldsymbol{\lambda}'_1 \mathbf{Y}_0)_+^{j-1} (z_2 - \boldsymbol{\lambda}'_2 \mathbf{Y}_t)_+^{j-1}] - \mathcal{J}_j(z_1, \boldsymbol{\lambda}_1; F)\mathcal{J}_j(z_2, \boldsymbol{\lambda}_2; F),\end{aligned}$$

with $(z_1, z_2)' \in \mathbb{R}^2$ and $(\boldsymbol{\lambda}'_1, \boldsymbol{\lambda}'_2)' \in \mathbb{L}^2$.

C Proof of Proposition A.1

The proposition below is used in the development of the bootstrap in the next section, appendix D.

Proposition A.1: Let c_j be a positive finite constant, then:

A(i) if H_0^j is true,

$$\lim_{N, M \rightarrow \infty} P(\text{reject } H_0^j) \leq P(\bar{S}_j^F \succ c_j) \equiv \alpha_F(c_j)$$

with equality when $F(z) = G(z)$ for all $z \in [0, \bar{z}]$;

A(ii) if H_0^j is true,

$$\lim_{N, M \rightarrow \infty} P(\text{reject } H_0^j) \leq P(\bar{S}_j^{G, F} \succ c_j) \equiv \alpha_{G, F}(c_j)$$

with equality when $F(z) = G(z)$ for all $z \in [0, \bar{z}]$;

B if H_0^j is false,

$$\lim_{N, M \rightarrow \infty} P(\text{reject } H_0^j) = 1.$$

The result provides a random variable that dominates the limiting random variable corresponding to the test statistic under the null hypothesis. The inequalities in *A(i)* and *A(ii)* imply that the tests will never reject more often than $\alpha_F(c_j)$ (respectively $\alpha_{G, F}(c_j)$) for any G satisfying the null hypothesis. As noted in the result the probability of rejection will asymptotically be exactly $\alpha_F(c_j)$ when $F = G$ ($\alpha_{G, F}(c_j)$ respectively), and, moreover,

$\alpha_F(c_j) = \alpha_{G,F}(c_j)$ because of the fact that $\overline{S}_j^{G,F} \stackrel{d}{=} \overline{S}_j^F$. The inequalities in $A(i)$ and $A(ii)$ imply that if one could find a c_j to set the $\alpha_F(c_j)$ (respectively $\alpha_{G,F}(c_j)$) to some desired probability level (say the conventional 0.05 or 0.01) then this would be the significance level for composite null hypotheses in the sense described by Lehmann (1986). The equality in B indicates that the test is capable of detecting any violation of the full set of restrictions of the null hypothesis. Of course, in order to make the result operational, we need to find an appropriate critical value c_j to satisfy $P(\overline{S}_j^F \succ c_j) \equiv \alpha$ or $P(\overline{S}_j^{G,F} \succ c_j) \equiv \alpha$. Since the distribution of the test statistic depends on the underlying distribution, this is not an easy task, and we rely on numerical simulation methods to simulate p-values such as the bootstrap.

D Simulating p-values

D.1 Bootstrap Methods

We provide bootstrap methods based on Proposition A.1($A(i)$) and A.1($A(ii)$) of the previous section, appendix B. In this case we define the sample as $\chi = \{X_1, \dots, X_N\}$ and compute the distribution of the random quantity

$$\overline{S}_j^F = \sqrt{N} \sup_z (\zeta_j(z; \widehat{F}_N^*) - \zeta_j(z; \widehat{F}_N)) \quad (\text{D.1})$$

where

$$\widehat{F}_N^*(z) = \frac{1}{N} \sum_{i=1}^N \mathbb{I}(X_i^* \leq z)$$

for a random sample of X_i^* drawn from χ . To simulate the random variable corresponding to $\overline{S}_j^{F,G}$ from Proposition A.1($A(ii)$), we use Van der Vaart and Wellner (1996) and resample the combined samples: $\mathfrak{Z} = \{X_1, \dots, X_N, Y_1, \dots, Y_M\}$. Let \widehat{G}_M^* denote the empirical CDF of a random sample of size M from \mathfrak{Z} and let \widehat{F}_N^* denote the empirical CDF of a random sample of size N from \mathfrak{Z} . Then we can compute the distribution of a random quantity

$$\overline{S}_{j,1}^{F,G} = \sqrt{\frac{NM}{N+M}} \sup_z (\zeta_j(z; \widehat{G}_M^*) - \zeta_j(z; \widehat{F}_N^*)). \quad (\text{D.2})$$

Let $\gamma = \{Y_1, \dots, Y_M\}$. The third method of bootstrapping can be done by drawing sample size of N from χ (with replacement) to construct an estimate of \widehat{F}_N^* and drawing samples of

size M from γ to construct an estimate of \widehat{G}_M^* , so we can compute the statistic

$$\overline{S}_{j,2}^{F,G} = \sqrt{\frac{NM}{N+M}} \sup_z ((\zeta_j(z; \widehat{G}_M^*) - \zeta_j(z; \widehat{G}_M)) - (\zeta_j(z; \widehat{F}_N^*) - \zeta_j(z; \widehat{F}_N))). \quad (\text{D.3})$$

For each case we can do Monte Carlo simulation to simulate the p-values. We can denote the p-values by the notion $\widetilde{p}_j^F, \widetilde{p}_{j,1}^{F,G}, \widetilde{p}_{j,2}^{F,G}$ respectively.

Proposition 1: Assuming that $\alpha < \frac{1}{2}$, a test for *SDJ* based on either rule: (see BD, Proposition 3)

$$\begin{aligned} &\text{reject } H_0^j \text{ if } \widetilde{p}_j^F < \alpha, \\ &\text{reject } H_0^j \text{ if } \widetilde{p}_{j,1}^{F,G} < \alpha, \\ &\text{reject } H_0^j \text{ if } \widetilde{p}_{j,2}^{F,G} < \alpha, \end{aligned}$$

satisfies the following:

$$\begin{aligned} \lim P(\text{reject } H_0^j) &\leq \alpha \text{ if } H_0^j \text{ is true,} \\ \lim P(\text{reject } H_0^j) &= 1 \text{ if } H_1^j \text{ is true.} \end{aligned}$$

The importance of the BD methodology is that it can be applied to different sample sizes over time and even for small sample sizes (e.g. sample size of 50) the power is quite good.

D.2 Block Bootstrap Methods

Block bootstrap methods extend the nonparametric i.i.d. bootstrap to a time series context (see BD and Abadie (2002) for use of the nonparametric i.i.d. bootstrap in stochastic dominance tests). They are based on “blocking” arguments, in which data are divided into blocks and those, rather than individual data, are resampled in order to mimic the time dependent structure of the original data. We focus on the block bootstrap since we face moderate sample sizes in the empirical applications, and wish to exploit the full sample information.

Let b, l denote integers such that $T = bl$. The non-overlapping rule (Carlstein (1986)) just asks the data to be divided into b disjoint blocks, the k th being $\mathbf{B}_k = (\mathbf{Y}'_{(k-1)l+1}, \dots, \mathbf{Y}'_{kl})'$ with $k \in \{1, \dots, b\}$. The block bootstrap method requires that we choose blocks $\mathbf{B}_1^*, \dots, \mathbf{B}_b^*$ by resampling randomly, with replacement, from the set of non-overlapping blocks. If $\mathbf{B}_i^* = (\mathbf{Y}_{i1}^{*'}, \dots, \mathbf{Y}_{il}^{*'})'$, a block bootstrap sample $\{\mathbf{Y}_t^*; t = 1, \dots, T\}$ is made of $\{\mathbf{Y}_{11}^*, \dots, \mathbf{Y}_{1l}^*, \mathbf{Y}_{21}^*, \dots, \mathbf{Y}_{2l}^*, \dots, \mathbf{Y}_{b1}^*, \dots,$ and we let \widehat{F}^* denote its empirical distribution.

Let us define $p_j^* := P[S_j^* > \widehat{S}_j]$, where S_j^* is the test statistic corresponding to each bootstrap sample. Then the block bootstrap method is justified by the next statement (see ST for the proof).

Proposition 2: Assuming that $\alpha < 1/2$, a test for SDE_j based on the rule:

$$\text{reject } H_0^j \quad \text{if } p_j^* < \alpha,$$

satisfies the following

$$\begin{aligned} \lim P[\text{reject } H_0^j] &\leq \alpha \text{ if } H_0^j \text{ is true,} \\ \lim P[\text{reject } H_0^j] &= 1 \text{ if } H_0^j \text{ is false.} \end{aligned}$$

In practice we need to use Monte Carlo methods to approximate the probability. The p-value is simply approximated by $\tilde{p}_j = \frac{1}{R} \sum_{r=1}^R \mathbb{I}\{\tilde{S}_{j,r} > \hat{S}_j\}$, where the averaging is made on R replications. The replication number can be chosen to make the approximations as accurate as we desire given time and computer constraints.

Note that other resampling methods such as subsampling are also available (see Linton et al. (2005) for the standard stochastic dominance tests). Linton et al. (2005) propose a procedure for estimating the critical values of the extended Kolmogorov-Smirnov tests of SD1 and SD2, allowing for the observations to be serially dependent. Since the HDI and its components are dependent among each other and each component is serially correlated, their subsampling approach can be used in our case. Linton et al. (2005) found that the subsampling approach works better for sample sizes of at least 500, however the bootstrap works better for smaller samples. We will use both the bootstrap method and the Linton et al.(2005) subsampling to test stochastically for improvement of the HDI over time.

E Mathematical formulations

E.1 Mathematical formulation of SD1 efficiency

The initial formulation for the test statistic \hat{S}_1 for first order stochastic dominance efficiency is Model (4.1).

We reformulate the problem in order to reduce the solving time and to obtain a tractable formulation. The steps are the following:

- 1) The factor \sqrt{T}/T can be left out in the objective function, since T is fixed.
- 2) We can see that there is a set of at most T values, say $\mathcal{R} = \{r_1, r_2, \dots, r_T\}$, containing the optimal value of the variable z .

Proof: Vectors $\boldsymbol{\tau}$ and \mathbf{Y}_t , $t = 1, \dots, T$ being given, we can rank the values of $\boldsymbol{\tau}'\mathbf{Y}_t$, $t =$

$1, \dots, T$, by increasing order. Let us call r_1, \dots, r_T the possible different values of $\boldsymbol{\tau}'\mathbf{Y}_t$, with $r_1 < r_2 < \dots < r_T$ (actually there may be less than T different values). Now, for any z such that $r_i \leq z \leq r_i + 1$, $\sum_{t=1, \dots, T} L_t$ is constant (it is equal to the number of t such that $\boldsymbol{\tau}'\mathbf{Y}_t \leq r_i$).

Further, when $r_i \leq z \leq r_i + 1$, the maximum value of $-\sum_{t=1, \dots, T} W_t$ is reached for $z = r_i$.

Hence, we can restrict z to belong to the set \mathcal{R} .

3) A direct consequence is that we can solve the original problem by solving the smaller problems $P(r)$, $r \in \mathcal{R}$, in which z is fixed to r . Then we take the value for z that yields the best total result. The advantage is that the optimal values of the L_t variables are known in $P(r)$. Precisely, $\sum_{t=1, \dots, T} L_t$ is equal to the number of t such that $\boldsymbol{\tau}'\mathbf{Y}_t \leq r$. Hence problem $P(r)$ boils down to:

$$\begin{aligned}
& \min \sum_{t=1}^T W_t \\
& \text{s.t. } M(W_t - 1) \leq r - \boldsymbol{\lambda}'\mathbf{Y}_t \leq MW_t, \quad \forall t \in T \\
& \quad \mathbf{e}'\boldsymbol{\lambda} = 1, \\
& \quad \boldsymbol{\lambda} \geq 0, \\
& \quad W_t \in \{0, 1\}, \quad \forall t \in T.
\end{aligned} \tag{E.1a}$$

Note that this becomes a minimization problem.

Problem $P(r)$ amounts to find the largest set of constraints $\boldsymbol{\lambda}'\mathbf{Y}_t \geq r$ consistent with $\mathbf{e}'\boldsymbol{\lambda} = 1$ and $\boldsymbol{\lambda} \geq 0$.

Let $M_t = \min \mathbf{Y}_{t,i}, i = 1, \dots, n$, i.e., the smallest entry of vector \mathbf{Y}_t .

Clearly, for all $\boldsymbol{\lambda} \geq 0$ such that $\mathbf{e}'\boldsymbol{\lambda} = 1$, we have that $\boldsymbol{\lambda}'\mathbf{Y}_t \geq M_t$. Hence, Problem $P(r)$ can be rewritten in an even better reduced form:

$$\begin{aligned}
& \min \sum_{t=1}^T W_t \\
& \text{s.t. } \boldsymbol{\lambda}'\mathbf{Y}_t \geq r - (r - M_t)W_t, \quad \forall t \in T \\
& \quad \mathbf{e}'\boldsymbol{\lambda} = 1, \\
& \quad \boldsymbol{\lambda} \geq 0, \\
& \quad W_t \in \{0, 1\}, \quad \forall t \in T.
\end{aligned} \tag{E.2a}$$

We further simplify $P(r)$ by fixing the following variables:

- for all t such that $r \leq M_t$, the optimal value of W_t is equal to 0 since the half space defined by the t -th inequality contains the simplex.

- for all t such that $r \geq M_t$, the optimal value of W_t is equal to 1 since the half space defined by the t -th inequality has an empty intersection with the simplex.

The computational time for this mixed integer programming formulation is significantly reduced. For the optimal solution (which involves 1264 mixed integer optimization programs, one for each discrete value of z) it takes less than two days. The problems are optimized with IBM's OSL solver on an IBM workstation with a 2*2.4 GHz Power, 6Gb of RAM. We note the almost exponential increase in solution time with an increasing number of observations. We stress here the computational burden that is managed for these tests. The optimization problems are modelled using the General Algebraic Modeling System (GAMS). The GAMS is a high-level modeling system for mathematical programming and optimization. It consists of a language compiler and a stable of integrated high-performance solvers. GAMS is tailored for complex, large scale modeling applications. The OSL solver uses the branch and bound technique to solve the MIP program.²⁰

E.2 Formulation of the SD2 problem

The model to derive the test statistic \hat{S}_2 for SD2 efficiency is the following:

$$\max_{z, \lambda} \hat{S}_2 = \sqrt{T} \frac{1}{T} \sum_{t=1}^T (L_t - W_t) \quad (\text{E.3a})$$

$$\text{s.t. } M(F_t - 1) \leq z - \boldsymbol{\tau}'\mathbf{Y}_t \leq MF_t, \quad \forall t, \quad (\text{E.3b})$$

$$-M(1 - F_t) \leq L_t - (z - \boldsymbol{\tau}'\mathbf{Y}_t) \leq M(1 - F_t), \quad \forall t, \quad (\text{E.3c})$$

$$-MF_t \leq L_t \leq MF_t, \quad \forall t \quad (\text{E.3d})$$

$$W_t \geq z - \boldsymbol{\lambda}'\mathbf{Y}_t, \quad \forall t, \quad (\text{E.3e})$$

$$\mathbf{e}'\boldsymbol{\lambda} = 1, \quad (\text{E.3f})$$

$$\boldsymbol{\lambda} \geq 0, \quad (\text{E.3g})$$

$$W_t \geq 0, F_t \in \{0, 1\}, \quad \forall t \quad (\text{E.3h})$$

with M being a large constant.

The model is a mixed integer program maximizing the distance between the sum over

²⁰The computational time for the formulation of this problem for a typical run is less than six hours.

all scenarios of two variables, $\frac{1}{T} \sum_{t=1}^T L_t$ and $\frac{1}{T} \sum_{t=1}^T W_t$ which represent the $\mathcal{J}_2(z, \boldsymbol{\tau}; \hat{F})$ and $\mathcal{J}_2(z, \boldsymbol{\lambda}; \hat{F})$, respectively. This is difficult to solve since it is the maximization of the difference of two convex functions. We use a binary variable F_t , which, according to inequalities (E.3b), equals 1 for each scenario $t \in T$ for which $z \geq \boldsymbol{\tau}'\mathbf{Y}_t$, and 0 otherwise. Then, inequalities (E.3c) and (E.3d) ensure that the variable L_t equals $z - \boldsymbol{\tau}'\mathbf{Y}_t$ for the scenarios for which this difference is positive, and 0 for all the other scenarios. Inequalities (E.3e) and (E.3h) ensure that W_t equals exactly the difference $z - \boldsymbol{\lambda}'\mathbf{Y}_t$ for the scenarios for which this difference is positive, and 0 otherwise. Equation (E.3f) defines the sum of all index weights to be unity, while inequality (E.3g) disallows negative weights.

Again, this is a very difficult problem to solve. The model is easily transformed to a linear one, which is much easier to solve.

We solve for SD2 efficiency by solving again smaller problems $P(r)$, $r \in \mathcal{R}$, in which z is fixed to r , before taking the value for z that yields the best total result.

The new model is the following:

$$\begin{aligned}
& \min \sum_{i=1}^T \sum_{t=1}^T W_{i,t} \\
& \text{s.t. } W_{i,t} \geq r_i - \boldsymbol{\lambda}'_i \mathbf{Y}_t, \quad \forall i, \quad \forall t \in T \\
& \quad \mathbf{e}' \boldsymbol{\lambda}_i = 1, \quad \forall i, \\
& \quad \boldsymbol{\lambda}_i \geq 0, \quad \forall i, \\
& \quad W_{i,t} \geq 0, \quad \forall i, \quad \forall t.
\end{aligned} \tag{E.4a}$$

The optimal hybrid index $\boldsymbol{\lambda}_i$ and the optimal value r_i of variable z are for that i , that gives $\min \sum_{t=1}^T W_{i,t}$.

Table 1 Simulation experiments

Simulation case 1: $X_1 \sim N(0.5, 0.1)$, $X_2 \sim N(0.5, 0.1)$ and $X_3 \sim N(0.5, 0.1)$				
Distance $\frac{1}{T} [F_\tau - F_\lambda]$	Number of equal indices	X1	X2	X3
0	164	0.3338	0.3399	0.3263
Dominance of same distributions is tested. 500 observations are simulated for all three components that are normally distributed with the same mean, 0.5, and the same standard, 0.1. The first column presents the largest distributional distance between the given (equally-weighted) index and any possible alternative. The second column presents the number of composite indices from 500 observations that have the same distribution as the equally-weighted index and the last three columns are the average weights of the same distributions.				

Simulation case 2: $X_1 \sim N(0.5, 0.15)$, $X_2 \sim N(0.5, 0.1)$ and $X_3 \sim N(0.5, 0.05)$				
Distance $\frac{1}{T} [F_\tau - F_\lambda]$	Number of dominating indices	X1	X2	X3
0.00001	203	0.0822	0.2589	0.6589
Dominance of different distributions is tested. 500 observations are simulated for all three components that are normally distributed with the same mean values, 0.5, but now different standard deviations are allowed for each component, 0.15, 0.1 and 0.05 respectively. The first column presents the largest distributional distance between the given (equally-weighted) index and any possible alternative. The second column presents the number of indices from 500 observations that dominate the equally-weighted index and the last three columns are the average weights of the dominating indices for each component.				

Simulation case 3: $X_1 \sim N(0.55, s_1)$, $X_2 \sim N(0.5, s_2)$ and $X_3 \sim N(0.45, s_3)$					
Combinations of different standard deviations	Distance $\frac{1}{T} [F_\tau - F_\lambda]$	Number of dominating indices	X1	X2	X3
sd1=sd2=sd3=0.1	0.04999	390	0.7723	0.1945	0.0332
sd1=0.15>sd2=0.1>sd3=0.05	0.05003	317	0.7020	0.2694	0.0286
sd1=0.15>sd3=0.1>sd2=0.05	0.05002	383	0.5190	0.4725	0.0085
sd3=0.15>sd2=0.1>sd1=0.05	0.05001	291	0.9264	0.0569	0.0167
sd3=0.15>sd1=0.1>sd2=0.05	0.04997	397	0.6637	0.3240	0.0123
sd2=0.15>sd3=0.1>sd1=0.05	0.05004	252	0.9468	0.0438	0.0094
sd2=0.15>sd1=0.1>sd3=0.05	0.05001	344	0.8383	0.1119	0.0497
Dominance of different distributions is tested. There are seven different simulation experiments take place in this case. 500 observations are simulated for all three components that are normally distributed with the different mean values, 0.55, 0.5, and 0.45. Different standard deviation combinations for each component are allowed for the seven simulation experiments. The first column of the table presents the combinations of different standard deviations. First row, each component has the same standard deviation, 0.1. The remaining six rows have all possible combinations of standard deviations for each component from a set of 0.05, 0.1, and 0.15. The second column presents the largest distributional distance between the given (equally-weighted) index and any possible alternative. The third column offers the number of indices from 500 observations that dominate the equally-weighted index and the last three columns are the average weights of the dominating indices for each component.					

Table 1 continued

Simulation case 4: Results with extra 100 entrants						
Rows	Number of observations	Number of dominating indices	Distributions of the simulated data	Average of dominating indices		
	N	n	Existing distribution of variables with 500 observations	X1	X2	X3
	500	498	$X_1 \sim N(0.55, 0.1), X_2 \sim N(0.5, 0.1), X_3 \sim N(0.45, 0.1)$	0.7723	0.1945	0.0332
Rows			Distribution of each variable for extra 100 entrants	Average of dominating indices after extra 100 entrants		
Row 1	600	597	$X_1 \sim N(0.6, 0.15), X_2 \sim N(0.5, 0.1), X_3 \sim N(0.45, 0.1)$	0.7649	0.2009	0.0342
Row 2	600	597	$X_1 \sim N(0.6, 0.1), X_2 \sim N(0.5, 0.1), X_3 \sim N(0.45, 0.1)$	0.7719	0.1960	0.0321
Row 3	600	597	$X_1 \sim N(0.6, 0.05), X_2 \sim N(0.5, 0.1), X_3 \sim N(0.45, 0.1)$	0.7926	0.1772	0.0302
Row 4	600	595	$X_1 \sim N(0.55, 0.1), X_2 \sim N(0.6, 0.15), X_3 \sim N(0.45, 0.1)$	0.7589	0.2094	0.0317
Row 5	600	597	$X_1 \sim N(0.55, 0.1), X_2 \sim N(0.6, 0.1), X_3 \sim N(0.45, 0.1)$	0.7594	0.2082	0.0324
Row 6	600	596	$X_1 \sim N(0.55, 0.1), X_2 \sim N(0.6, 0.05), X_3 \sim N(0.45, 0.1)$	0.7447	0.2269	0.0284
Row 7	600	595	$X_1 \sim N(0.55, 0.1), X_2 \sim N(0.5, 0.1), X_3 \sim N(0.6, 0.15)$	0.7832	0.1724	0.0444
Row 8	600	596	$X_1 \sim N(0.55, 0.1), X_2 \sim N(0.5, 0.1), X_3 \sim N(0.6, 0.1)$	0.7875	0.1770	0.0355
Row 9	600	596	$X_1 \sim N(0.55, 0.1), X_2 \sim N(0.5, 0.1), X_3 \sim N(0.6, 0.05)$	0.7768	0.1702	0.0530
<p>Dominance of different distributions is tested once heterogeneous entries are allowed to enter the existing data. An extra 100 more observations with heterogeneous distributions are allowed to enter the existing distribution with 500 observations. The second column of the table presents the number of observations after heterogeneous entries, 600. The third column presents the number of dominating indices from 600 observations. The fourth column offers the details of existing distribution of variables with 500 observations and the distribution of each variable for extra entrants. Nine possible heterogeneous entries are allowed for each component. For the first three rows, 100 new entrants of the second and third components have the same distribution as existing data but the first component has a mean value of 0.6 and different standard deviation combinations, 0.15, 0.1, and 0.05 respectively. From row 4 to 6, the first and third components have the same distributions as the existing distribution and different entries are allowed for the second component. From row 7 to 9, the first and second components have the same distributions as the existing distribution and different entries are allowed for the third component. The last three columns present the average of the dominating weighting indices for each case.</p>						

Table 2 Descriptive Statistics

Human development index						
Year	1975	1980	1985	1990	1995	2000
Sample size	101	113	121	136	146	138
Mean	0.60	0.63	0.64	0.67	0.68	0.70
Median	0.62	0.66	0.68	0.71	0.73	0.74
Standard deviation	0.20	0.19	0.19	0.18	0.18	0.18

Education index						
Year	1975	1980	1985	1990	1995	2000
Sample size	101	113	121	136	146	138
Mean	0.59	0.64	0.67	0.71	0.73	0.76
Median	0.62	0.68	0.73	0.78	0.81	0.83
Standard deviation	0.26	0.24	0.23	0.22	0.21	0.20

Life expectancy index						
Year	1975	1980	1985	1990	1995	2000
Sample size	101	113	121	136	146	138
Mean	0.57	0.62	0.64	0.66	0.67	0.67
Median	0.57	0.63	0.66	0.71	0.72	0.74
Standard Deviation	0.18	0.17	0.17	0.18	0.19	0.20

GDP index						
Year	1975	1980	1985	1990	1995	2000
Sample size	101	113	121	136	146	138
Mean	0.62	0.65	0.64	0.65	0.65	0.66
Median	0.61	0.64	0.63	0.64	0.65	0.66
Standard Deviation	0.18	0.18	0.19	0.19	0.19	0.20

Table 3 Stochastic dominance results with BD (2003) sampling approach

Stochastic dominance results for human development index						
		1975	1980	1985	1990	1995
1980	SD1	N/A	-	-	-	-
	SD2	10%	-	-	-	-
1985	SD1	N/A	N/A	-	-	-
	SD2	1-5%	N/A	-	-	-
1990	SD1	1%	N/A	N/A	-	-
	SD2	1-5%	5-10%	N/A	-	-
1995	SD1	1%	10%	10%	N/A	-
	SD2	1%	5%	10%	N/A	-
2000	SD1	1%	5%	1%	10%	N/A
	SD2	1%	1%	1%	10%	N/A

The vertical column represents the years from 1980 to 2000 that are tested for stochastic dominance against years from 1975 to 1995. Percentage levels in the table represent the significance level of stochastic dominance. N/A represents that there is no dominance at that order.

Stochastic dominance results for education index						
		1975	1980	1985	1990	1995
1980	SD1	N/A	-	-	-	-
	SD2	10%	-	-	-	-
1985	SD1	5%	N/A	-	-	-
	SD2	1-5%	N/A	-	-	-
1990	SD1	1%	10%	N/A	-	-
	SD2	1%	1%	5-10%	-	-
1995	SD1	1%	5%	5%	N/A	-
	SD2	1%	1%	1%	N/A	-
2000	SD1	1%	1%	1%	5%	N/A
	SD2	1%	1%	1%	1-5%	10%

The vertical column represents the years from 1980 to 2000 that are tested for stochastic dominance against years from 1975 to 1995. Percentage levels in the table represent the significance level of stochastic dominance. N/A represents that there is no dominance at that order.

Stochastic dominance results for life expectancy index						
		1975	1980	1985	1990	1995
1980	SD1	N/A	-	-	-	-
	SD2	1-5%	-	-	-	-
1985	SD1	5%	N/A	-	-	-
	SD2	1%	N/A	-	-	-
1990	SD1	1%	5%	N/A	-	-
	SD2	1%	1-5%	N/A	-	-
1995	SD1	1%	1%	5%	N/A	-
	SD2	1%	1-5%	10%	N/A	-
2000	SD1	1%	1%	5%	10%	N/A
	SD2	1%	1%	10%	10%	N/A

The vertical column represents the years from 1980 to 2000 that are tested for stochastic dominance against years from 1975 to 1995. Percentage levels in the table represent the significance level of stochastic dominance. N/A represents that there is no dominance at that order.

Table 3 continued

Stochastic dominance results for GDP index						
		1975	1980	1985	1990	1995
1980	SD1	N/A	-	-	-	-
	SD2	N/A	-	-	-	-
1985	SD1	N/A	N/A	-	-	-
	SD2	N/A	N/A	-	-	-
1990	SD1	N/A	N/A	N/A	-	-
	SD2	N/A	N/A	N/A	-	-
1995	SD1	N/A	N/A	N/A	N/A	-
	SD2	N/A	N/A	N/A	N/A	-
2000	SD1	N/A	N/A	N/A	N/A	N/A
	SD2	5-10%	N/A	N/A	N/A	N/A

The vertical column represents the years from 1980 to 2000 that are tested for stochastic dominance against years from 1975 to 1995. Percentage levels in the table represent the significance level of stochastic dominance. N/A represents that there is no dominance at that order.

Table 4 Stochastic dominance results with Linton et al. (2005) subsampling approach

Stochastic dominance results for human development index						
		1975	1980	1985	1990	1995
1980	SD1	0.896	-	-	-	-
	SD2	0.582	-	-	-	-
1985	SD1	0.892	0.837	-	-	-
	SD2	0.441	0.569	-	-	-
1990	SD1	0.885	0.884	0.801	-	-
	SD2	0.557	0.437	0.470	-	-
1995	SD1	0.517	0.941	0.797	0.535	-
	SD2	0.420	0.532	0.555	0.804	-
2000	SD1	0.758	0.936	0.915	0.768	0.870
	SD2	0.416	0.439	0.519	0.424	0.447

The vertical column represents the years from 1980 to 2000 that are tested for stochastic dominance against years from 1975 to 1995. P-values for the null hypothesis that the given index in the following years dominates the index of the previous years are reported.

Stochastic dominance results for education index						
		1975	1980	1985	1990	1995
1980	SD1	0.814	-	-	-	-
	SD2	0.402	-	-	-	-
1985	SD1	0.856	0.880	-	-	-
	SD2	0.401	0.604	-	-	-
1990	SD1	0.720	0.795	0.844	-	-
	SD2	0.448	0.584	0.729	-	-
1995	SD1	0.582	0.830	0.990	0.000	-
	SD2	0.552	0.405	0.735	0.364	-
2000	SD1	0.821	0.622	0.989	0.547	0.879
	SD2	0.510	0.535	0.711	0.861	0.863

The vertical column represents the years from 1980 to 2000 that are tested for stochastic dominance against years from 1975 to 199. P-values for the null hypothesis that the given index in the following years dominates the index of the previous years are reported.

Stochastic dominance results for life expectancy index						
		1975	1980	1985	1990	1995
1980	SD1	0.995	-	-	-	-
	SD2	0.386	-	-	-	-
1985	SD1	0.517	0.866	-	-	-
	SD2	0.387	0.371	-	-	-
1990	SD1	0.650	0.650	0.018	-	-
	SD2	0.611	0.582	0.018	-	-
1995	SD1	0.650	0.570	0.803	0.031	-
	SD2	0.479	0.521	0.598	0.000	-
2000	SD1	0.569	0.490	0.557	0.004	0.012
	SD2	0.541	0.555	0.521	0.000	0.000

The vertical column represents the years from 1980 to 2000 that are tested for stochastic dominance against years from 1975 to 1995. P-values for the null hypothesis that the given index in the following years dominates the index of the previous years are reported.

Table 4 continued

Stochastic dominance results for GDP index						
		1975	1980	1985	1990	1995
1980	SD1	0.955	-	-	-	-
	SD2	0.578	-	-	-	-
1985	SD1	0.950	0.951	-	-	-
	SD2	0.429	0.686	-	-	-
1990	SD1	0.971	0.970	0.986	-	-
	SD2	0.534	0.568	0.609	-	-
1995	SD1	0.737	0.789	0.872	0.805	-
	SD2	0.553	0.573	0.583	0.376	-
2000	SD1	0.687	0.598	0.659	0.478	0.981
	SD2	0.621	0.622	0.559	0.613	0.678

The vertical column represents the years from 1980 to 2000 that are tested for stochastic dominance against years from 1975 to 1995. P-values for the null hypothesis that the given index in the following years dominates the index of the previous years are reported.

Table 5 Stochastic efficient weighting for human development index

Stochastic efficient weighting for human development index				
		Stochastic efficient weights		
Highest distance $\frac{1}{T}[F_{\tau} - F_{\lambda}]$	Number of indices that dominate fixed weighted HDI	Life expectancy index	Education index	GDP index
0.04540	293	0.1238	0.7117	0.1645
Stochastic efficient weights of life expectancy, educational attainment and standard of living that dominate the equally-weighted HDI are presented. Highest distance obtained between any alternative composite index and the equally-weighted HDI empirical distributions is given. There are 293 composite indices that dominate the equally-weighted index. The average of dominating indices offer the stochastic efficient weights assigned to each component.				

Table 6 Country rankings for years 1995, 2000 and 2006
(Using the most optimistic weighting scheme of the HDI and the standard equally-weighted HDI)

Top 20 country rankings with the most optimistic weighting scheme of HDI for years 1995, 2000 and 2006

Country	Rankings with the most optimistic scheme of the HDI in 1995 (in parenthesis rankings with standard HDI)	Country	Rankings with the most optimistic scheme of the HDI in 2000 (in parenthesis rankings with standard HDI)	Country	Rankings with the most optimistic scheme of the HDI in 2006 (in parenthesis rankings with standard HDI)
Canada	1 (1)	Belgium	1 (4)	Canada	1 (3)
United States	2 (4)	Australia	2 (5)	Norway	2 (2)
Finland	3 (6)	Sweden	3 (2)	Australia	3 (4)
Norway	4 (3)	Netherlands	4 (8)	Finland	4 (12)
New Zealand	5 (9)	Finland	5 (10)	Denmark	5 (13)
France	6 (2)	United States	6 (6)	Ireland	6 (5)
Netherlands	7 (7)	Norway	7 (1)	Iceland	7 (1)
Denmark	8 (18)	Canada	8 (3)	Netherlands	8 (6)
Belgium	9 (12)	United Kingdom	9 (13)	New Zealand	9 (20)
Spain	10 (11)	New Zealand	10 (19)	Luxembourg	10 (9)
Austria	11 (13)	Denmark	11 (14)	France	11 (11)
United Kingdom	12 (14)	France	12 (12)	Sweden	12 (7)
Ireland	13 (17)	Iceland	13 (7)	Greece	13 (18)
Iceland	14 (5)	Germany	14 (17)	Belgium	14 (17)
Sweden	15 (10)	Austria	15 (15)	United States	15 (15)
Germany	16 (19)	Ireland	16 (18)	Korea (Rep.of)	16 (25)
Japan	17 (8)	Spain	17 (21)	Spain	17 (16)
Australia	18 (15)	Switzerland	18 (11)	Austria	18 (14)
Greece	19 (20)	Japan	19 (9)	Italy	19 (19)
Switzerland	20 (16)	Italy	20 (20)	Japan	20 (8)

The ranking of countries with the most optimistic weighting scheme of the HDI are obtained by using the stochastic efficient weights offered in Table 5. Countries that are ranked at the top 20 with the most optimistic weighting scheme of the HDI in years 1995, 2000 and 2006 are reported. Rankings of countries with the standard equally-weighted HDI are also presented in parentheses.

Table 6 continued

Largest upward movements in rankings with the most optimistic weighting scheme of the HDI in years 1995, 2000 and 2006

Country	Largest upward movements in rankings in 1995	Country	Largest upward movements in rankings in 2000	Country	Largest upward movements in rankings in 2006
Turkmenistan	38	Uzbekistan	33	Guyana	37
Armenia	27	Turkmenistan	33	Ukraine	33
Ukraine	22	South Africa	31	Kazakhstan	30
Estonia	22	Moldova	31	Kyrgyzstan	28
Russia	22	Ukraine	30	Mongolia	26
Malawi	21	Malawi	27	Belarus	25
Uzbekistan	20	Kazakhstan	26	Turkmenistan	25
Philippines	20	Guyana	24	Russia	23
Samoa	20	Maldives	24	Lesotho	22
Kazakhstan	20	Armenia	24	Moldova	20
Poland	20	Tajikistan	22	Tonga	19
Belarus	19	Philippines	21	Georgia	19
Tajikistan	18	Zambia	20	Cuba	18
Kyrgyzstan	18	Rwanda	19	Samoa	18
Lithuania	17	Kyrgyzstan	19	Tajikistan	18
Grenada	16	Ecuador	18	Malawi	18
Zimbabwe	15	Russia	18	Lithuania	17
Georgia	15	Azerbaijan	17	Bolivia	16
Latvia	15	Suriname	16	Uganda	16
Korea, DPR	15	Vietnam	15	Zambia	16

The ranking of countries with the most optimistic weighting scheme of the HDI are obtained by using the stochastic efficient weights offered in Table 5. We report the 20 countries which have the largest upward movements in rankings with the most optimistic weighting scheme of the HDI vis-à-vis the standard equally-weighted HDI for years 1995, 2000 and 2006.

Table 6 continued

Largest downward movements in rankings with the most optimistic weighting scheme of the HDI in years 1995, 2000 and 2006

Country	Largest downward movements in rankings in 1995	Country	Largest downward movements in rankings in 2000	Country	Largest downward movements in rankings in 2006
Oman	-45	Kuwait	-47	Oman	-48
Saudi Arabia	-43	UAE	-45	UAE	-34
Belize	-35	Saudi Arabia	-38	Saudi Arabia	-32
Kuwait	-33	Oman	-36	Belize	-28
Algeria	-32	Qatar	-34	Iran	-25
UAE	-27	Malaysia	-29	Singapore	-24
Turkey	-25	Antigua and Barbuda	-26	Antigua and Barbuda	-23
Iran	-25	Mauritius	-26	Tunisia	-22
Tunisia	-24	Vanuatu	-26	Algeria	-21
Syrian Arab Rep.	-23	Hong Kong	-23	Turkey	-21
Malaysia	-22	Seychelles	-17	Pakistan	-19
Singapore	-20	Trinidad and Tobago	-17	Jamaica	-18
Hong Kong	-19	Saint Lucia	-16	Mauritius	-18
Mauritius	-18	Turkey	-16	Kuwait	-18
Egypt	-16	Mexico	-15	Qatar	-17
Morocco	-16	Tunisia	-15	Saint Vincent and the Grenadines	-16
Luxembourg	-15	Morocco	-15	Malaysia	-16
Qatar	-14	Pakistan	-14	Hong Kong	-16
Guatemala	-13	Brunei	-13	Senegal	-14
Botswana	-12	Algeria	-13	Bhutan	-14

The ranking of countries with the most optimistic weighting scheme of the HDI are obtained by using the stochastic efficient weights offered in Table 5. We report the 20 countries which have the largest downward movements in rankings with the most optimistic weighting scheme of the HDI vis-à-vis the standard equally-weighted HDI for years 1995, 2000 and 2006.

Table 7 Country distributions in different human development groups with the most optimistic weighting scheme of the HDI and with the official HDI over time

Country distributions in different human development groups with the official HDI			
Level of human development	Percentage of countries in 1995	Percentage of countries in 2000	Percentage of countries in 2006
Low human development ($HDI < 0.5$)	25	21	15
Medium human development ($0.8 > HDI \geq 0.5$)	38	49	44
High human development ($0.9 > HDI \geq 0.8$)	22	19	23
Very high human development ($HDI \geq 0.9$)	15	12	18
This table presents the percentages of countries that fall into four human development groups specified by the United Nations' Development Programme for the years 1995, 2000 and 2006 with the official HDI. Low, medium, high and very high human development groups consist of countries that have HDI values less than 0.5, between 0.5 and 0.799, between 0.8 and 0.799, and above 0.9 respectively.			

Country distributions in different human development groups with the most optimistic weighting scheme of the HDI			
Level of human development	Percentage of countries in 1995	Percentage of countries in 2000	Percentage of countries in 2006
Low human development ($HDI < 0.5$)	20	17	10
Medium human development ($0.8 > HDI \geq 0.5$)	37	36	31
High human development ($0.9 > HDI \geq 0.8$)	29	32	37
Very high human development ($HDI \geq 0.9$)	15	15	22
This table presents the percentages of countries that fall into four human development groups specified by the United Nations' Development Programme for the years 1995, 2000 and 2006 with the most optimistic weighting scheme of the HDI. Low, medium, high and very high human development groups consist of countries that have HDI values less than 0.5, between 0.5 and 0.799, between 0.8 and 0.799, and above 0.9 respectively.			