Autonomous Terminal Luggage Trolley Robert Bailey • Anand Patel • Thiviyan Sivakumar • Abdallah Younes

Background

- Currently, people with disablities require further assistance to transport their luggage throughout the airport.
- Existing trolley designs pose risks to nearby users and objects as potential collisions may occur due to luggage being stacked at unsafe



BARTY-T

heights.

Objective

- Provide better accessibility to people with disabilities, allowing them to act more independently.
- Improve on the ergonomics of current trolley designs by limiting the height luggage needs to be lifted.
- Reduce strain due to pushing heavy-loaded trolleys.
- Limit chances of collision with pedestrians or other objects.

Trolley Specifications

Max Luggage Weight	
--------------------	--

Tracker Range

50-100 m

128 kg

1-5 m

Proximity Sensor Range

1060 x 970 x 1870 mm

Dimensions

FN FS

Proposed Solution

- Four-wheeled autonomous cart with smart collision detection and avoidance mechanisms. Open and accessible design for easy loading and unloading of luggage.
- Wireless tracking and homing system to follow the airport patron using Bluetooth Low Energy (BLE) communication.
- Powered by electric motors and a rechargeable battery pack.

Conclusions

 Proof of concept successfully detects obstacles and avoids collisions. Cart accurately follows BLE tracker autonomously once activated.

Recommendations

- Different energy source.
- Uniquely encrypted Bluetooth signal to prevent interference with other trolleys.

Ability to sense luggage weight.





Faculty Advisor: Soha Moussa, Ph.D, P.Eng. Acknowledgements: Evan Fallis